

# G53CMP: Lecture 14

## Run-Time Organisation I

Henrik Nilsson

University of Nottingham, UK

G53CMP: Lecture 14 – p.1/37

## Storage Areas

- **Static storage:** storage for entities that live throughout an execution.
- **Stack storage:** storage allocated dynamically, but deallocation must be carried out in the opposite order to allocation.
- **Heap storage:** region of the memory where entities can be allocated and deallocated dynamically as needed, in any order.

G53CMP: Lecture 14 – p.3/37

## This Lecture

One aspect of run-time organisation:  
stack-based storage allocation

- Lifetime and storage
- Basic stack allocation:
  - stack frames
  - dynamic links
- Allocation for nested procedures:
  - non-local variable access
  - static links

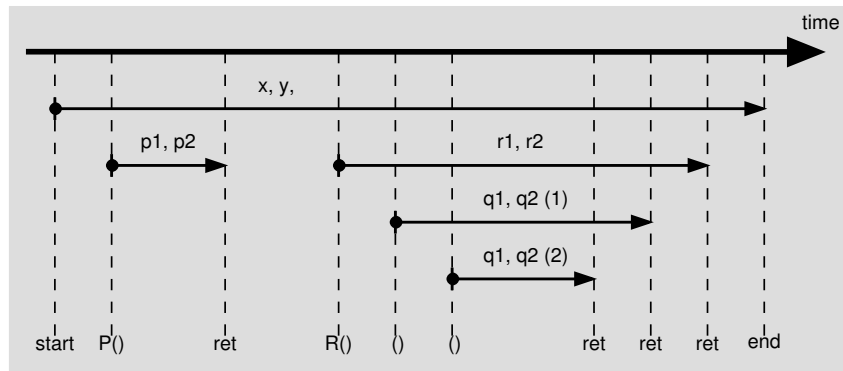
G53CMP: Lecture 14 – p.2/37

## Example: Lifetime (1)

```
var x, y: ...
proc P()
  var p1, p2: ...
  begin ... end
proc Q()
  var q1, q2: ...
  begin ... if ... Q(); ... end
proc R()
  var r1, r2: ...
  begin ... Q() ... end
begin ... P() ... R() ... end
```

G53CMP: Lecture 14 – p.4/37

## Example: Lifetime (2)



G53CMP: Lecture 14 – p.5/37

## Storage Allocation (1)

- **Global variables** exist throughout the program's run-time.
- Where to store such variables can thus be decided **statically**, at compile (or link) time, once and for all.

Example:

```
private static String [] tokenTable  
= ...
```

G53CMP: Lecture 14 – p.7/37

## Example: Lifetime (3)

```
private static Integer foo(int i) {  
    Integer n = new Integer(i);  
    return n;  
}
```

- The lifetimes of `i` and `n` coincides with the invocation of `foo`.
- The lifetime of the integer **object** created by `new` starts when `new` is executed and ends when there are no more references to it.
- The integer object thus **survives** the invocation of `foo`.

G53CMP: Lecture 14 – p.6/37

## Storage Allocation (2)

- **Arguments** and **local variables** exist only during a function (or procedure or method) invocation:
  - Function calls are properly nested.
  - In case of **recursion**, a function may be **re-entered** any number of times.
  - Each function activation needs a private set of arguments and local variables.
- These observations suggest that storage for arguments and local variables should be allocated on a **stack**.

G53CMP: Lecture 14 – p.8/37

## Storage Allocation (3)

- When the lifetime does not coincide with procedure/function invocations, **heap allocation** is needed. E.g. for:
  - objects in object-oriented languages
  - function closures in languages supporting functions as first class entities
  - storage allocated by procedures like `malloc` in C.
- Such storage either **explicitly deallocated** when no longer needed, or **automatically reclaimed** by a garbage collector.

GS3CMP: Lecture 14 – p.9/37

## Defining the Stack

The stack is usually defined by a handful of registers, dictated by the CPU architecture and/or convention. For example:

- **SB**: Stack Base
- **ST**: Stack Top
- **LB**: Local Base

The names vary. Stack Pointer (SP) and Frame Pointer (FP) are often used instead of ST and LB, respectively.

GS3CMP: Lecture 14 – p.11/37

## Stack Frames

One **stack frame** or **activation record** for each currently active function/procedure/method.  
Contents:

- Arguments
- Bookkeeping information; e.g.
  - Return address
  - Dynamic link
  - Static link
- Local variables
- Temporary workspace

GS3CMP: Lecture 14 – p.10/37

## Typical Stack Frame Layout

address	contents
LB - <i>argOffset</i>	arguments
...	...
LB	static link
LB + 1	dynamic link
LB + 2	return address
LB + 3	local variables
...	...
LB + <i>tempOffset</i>	temporary storage

where

$$argOffset = size(arguments)$$

$$tempOffset = 3 + size(local\ variables)$$

TAM uses this convention. (Word (e.g. 4 bytes) addressing assumed, offsets in **words**.)

GS3CMP: Lecture 14 – p.12/37

## Example: A function $f$

(Not quite current MiniTriangle, but language could easily be extended in this way.)

```

var n: Integer;
...
fun f(x,y: Integer): Integer =
  let
    z: Integer
  in begin
    z := x * x + y * y;
    return n * z
  end

```

G53CMP: Lecture 14 – p.13/37

## Example: Stack layout on entry to $f$

On entry to  $f$ ; caller's ST =  $f$ 's LB:

address	contents
...	...
SB + 42	n: $n$
...	...
LB - 2	x: 3
LB - 1	y: 7
LB	static link
LB + 1	dynamic link
LB + 2	return address = 2018

Ret. addr. = old program counter (PC) = addr. of instruction immediately after the call instruction.  
 New PC = address of first instruction of  $f$  = 2082.

G53CMP: Lecture 14 – p.15/37

## Example: Calling $f$

Call sequence for  $f(3, 7) * 8$ :

```

2015   LOADL 3       ; 1st arg. (x)
2016   LOADL 7       ; 2nd arg. (y)
2017   CALL  f
2018   LOADL 8
2019   MUL

```

Address of each instruction explicitly indicated to the left. Address of  $f$  here given symbolically by a label. Corresponds to the address where the code for  $f$  starts, say 2082.

G53CMP: Lecture 14 – p.14/37

## Example: TAM Code for $f$

TAM-code for the function  $f$  (at address 2082):

```

LOADL 0          ADD
LOAD  [LB - 2]; x  STORE  [LB + 3] ; z
LOAD  [LB - 2]; x  LOAD   [SB + 42]; n
MUL              LOAD   [LB + 3] ; z
LOAD  [LB - 1]; y  MUL
LOAD  [LB - 1]; y  POP    1 1
MUL              RETURN 1 2

```

RETURN replaces activation record (frame) of  $f$  by result, restores LB, and jumps to ret. addr. (2018).

Note: all variable offsets are *static*.

G53CMP: Lecture 14 – p.16/37

## Dynamic and Static Links

- **Dynamic Link:** Value to which `LB` (Local Base) is restored by `RETURN` when exiting procedure; i.e. addr. of **caller's frame** = old `LB`:
  - “Dynamic” because related to dynamic call graph.
- **Static Link:** Base of underlying frame of function that **immediately lexically encloses** this one.
  - “Static” because related to program’s static structure.
  - Used to determine addresses of variables of lexically enclosing functions.

## Example: Stack Allocation (1)

```

let
  var a: Integer[3];
  var b: Boolean;
  var c: Character;

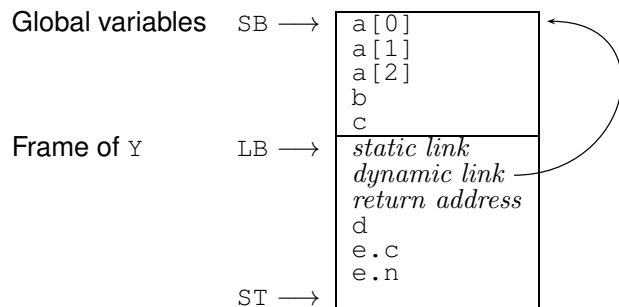
  proc Y ()
    let
      var d: Integer;
      var e: record c: Character, n: Integer end
    in
      ...;
  proc Z ()
    let
      var f: Integer
    in
      begin ...; Y(); ... end
  in
    begin ...; Y(); ...; Z(); ... end

```

## Example: Stack Allocation (2)

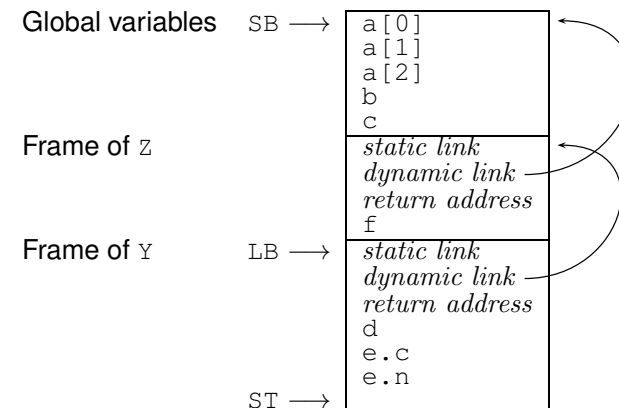
Initially `LB = SB`; i.e., the global variables constitute the frame of the main program.

Call sequence: `main → Y` (i.e. after `main` calling `Y`):

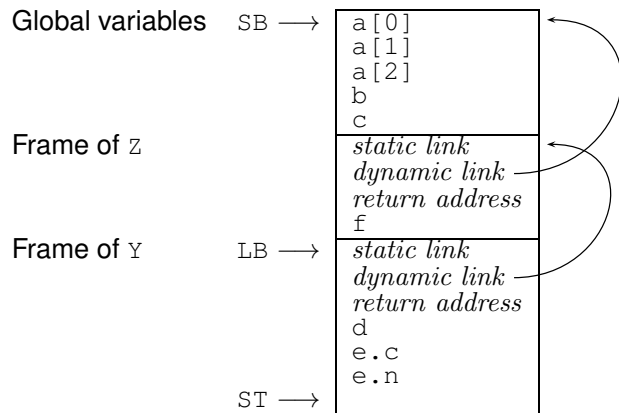


## Example: Stack Allocation (3)

Call sequence: `main → Z → Y`:



## Exercise: Stack Allocation



In Y, what is the address of: *b*? *e.c*? *f*?

## Non-Local Variable Access (1)

Consider *nested* procedures:

```

proc P()
  var x, y, z: Integer
  proc Q()
    ...
    begin ... if ... Q() ... end
  proc R()
    ...
    begin ... Q() ... end
  begin ... Q() ... R() ... end

```

P's variables are in scope also in Q and R.

But how to access them from Q or R?

Neither global, nor local!

Belong to the *lexically enclosing procedure*.

## Non-Local Variable Access (2)

In particular:

- We cannot access *x*, *y*, *z* relative to the stack base (*SB*) since we cannot (in general) statically know if *P* was called directly from the main program or indirectly via one or more other procedures.
- I.e., there could be arbitrarily many stack frames *below* *P*'s frame.

## Non-Local Variable Access (3)

- We cannot access *x*, *y*, *z* relative to the local base (*LB*) since we cannot (in general) statically know if e.g. *Q* was called directly from *P*, or indirectly via *R* and/or recursively via itself.
- I.e., there could be arbitrarily many stack frames *between* *Q*'s and *P*'s frames.

## Non-Local Variable Access (4)

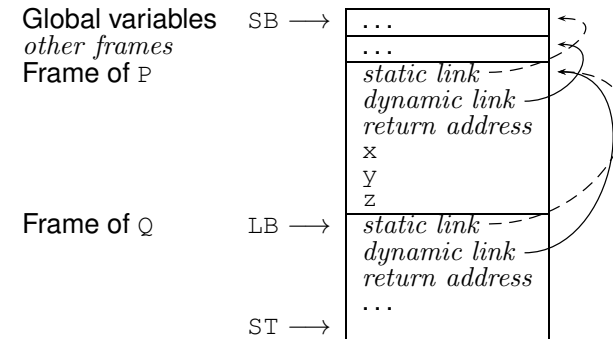
Answer:

- The **Static Links** in Q's and R's frames are set to point to P's frame on each activation.
- The static link in P's frame is set to point to the frame of **its** closest lexically enclosing procedure, and so on.
- Thus, by following the chain of static links, one can access variables at any level of a nested scope.

G53CMP: Lecture 14 – p.25/37

## Non-Local Variable Access (5)

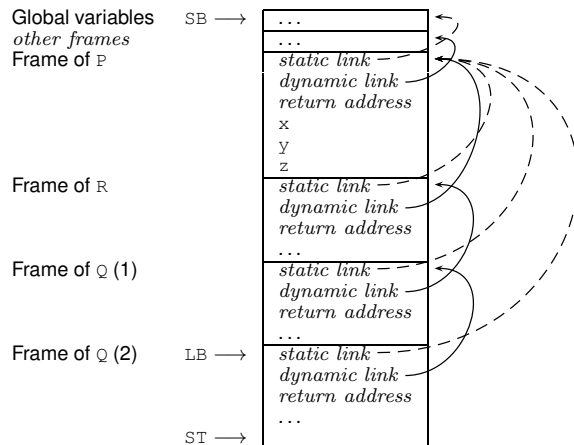
Call sequence: main → ... → P → Q:



G53CMP: Lecture 14 – p.26/37

## Non-Local Variable Access (6)

Call sequence: main → ... → P → R → Q → Q:



G53CMP: Lecture 14 – p.27/37

## Non-Local Variable Access (7)

Consider further levels of nesting:

```

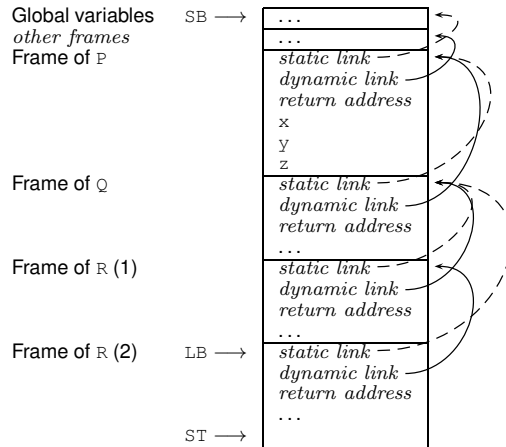
proc P()
  var x, y, z: Integer
  proc Q()
    proc R()
      ...
      begin ...if ... R() ... end
      ...
      begin ... R() ... end
    begin ... Q() ... end
  end
end
    
```

**Note:** Q's variables now in scope in R. To access, compute the **difference between scope levels** of the accessing procedure/function and the accessed variable (**note: static information**), and follow that many static links.

G53CMP: Lecture 14 – p.28/37

## Non-Local Variable Access (8)

Call sequence: main → ... → P → Q → R → R:



G53CMP: Lecture 14 – p.29/37

## Example: Non-local Access

Accessing *y* in *P* from within *R*; scope level difference is 2:

```
LOAD  [LB + 0] ; R's static link
LOADI 0        ; Q's static link
LOADI 4        ; y at offset 4 in P's frame
```

G53CMP: Lecture 14 – p.31/37

## Example: Call with Static Link

TAM code, *P* calling *Q*: *Q*'s static link = *P*'s local base, pushed onto stack prior to call:

```
LOADA  [LB + 0] ; Q's static link
LOADCA #1_Q     ; Address of Q
CALLI
```

TAM code, *R* calling itself recursively: copy of *R*'s static link (as callee's and caller's scope levels are the same) pushed onto stack prior to call:

```
LOAD  [LB + 0] ; R's static link
LOADCA #2_R    ; Address of R
CALLI
```

G53CMP: Lecture 14 – p.30/37

## Code Generation (1)

```
evaluate majl env (ExpVar {evVar = itms}) =
  case lookupISV itms env of
    ISVDisp d ->
      address majl vl d
    ISVLbl l -> do
      staticLink majl vl
      emit (LOADCA l)
```

where

```
vl = majScopeLvl (itmsLvl itms)
```

Note: A label represents a procedure or function; what is pushed onto stack is effectively the corresponding *closure* (see later slide).

G53CMP: Lecture 14 – p.32/37



## Code Generation (2)

```
address :: Int -> Int -> MInt -> TAMCG ()
address cl vl d
  | vl == topMajScopeLvl = Variable Scope Level
    emit (LOADA (SB d))
  | cl == vl = Current Scope Level
    emit (LOADA (LB d))
  | cl > vl = do
    emit (LOAD (LB sld))
    emitN (cl - vl - 1) (LOADI sld)
    emit (LOADL d)
    emit ADD
  | otherwise = error "Bug: Not in scope!"
```

G53CMP: Lecture 14 - p.33/37

## Closures (1)

A **closure**:

- Code for function or procedure; and
- Bindings for all its free variables.

Under the present scheme:

- Code: Address of function or procedure;
- Bindings: Chain of stack-allocated activation records linked by the static links.

Works only when closure does not survive the activation of the function/procedure where it was created.

**Cannot** support first-class functions/procedures!

G53CMP: Lecture 14 - p.35/37

## Code Generation (3)

```
staticLink :: Int -> Int -> TAMCG ()
staticLink crl cel
  | cel == topMajScopeLvl = Callee Scope Level
    emit (LOADL 0)
  | crl == cel = Caller Scope Level
    emit (LOADA (LB 0))
  | crl > cel = do
    emit (LOAD (LB sld))
    emitN (crl - cel - 1) (LOADI sld)
  | otherwise =
    error "Bug: Not in scope!"
```

G53CMP: Lecture 14 - p.34/37

## Closures (2)

- Functions/procedures are **first class** if they can be handled just like any other values; e.g.
  - bound to variables
  - passed as arguments
  - **returned** as results.
- Supporting first-class functions/procedures requires closures to be **heap-allocated**:
  - Code still just address of function or procedure.
  - Static link replaced by (pointer(s) to) heap-allocated activation record(s).

G53CMP: Lecture 14 - p.36/37

## Closures (3)

- As an optimisation, one could imagine combined schemes: stack allocation and static links might be used when known that a closure will never survive activation of enclosing function/procedure.