

# G54FOP: Lecture 12

## *Types and Type Systems I*

Henrik Nilsson

University of Nottingham, UK

G54FOP: Lecture 12 – p.1/34

## Types and Type Systems (1)

Type systems are an example of **lightweight formal methods**:

- highly automated
- but with limited expressive power.

A plausible definition (Pierce):

*A type system is a tractable syntactic method for proving the absence of certain program behaviors by classifying phrases according to the kinds of values they compute.*

G54FOP: Lecture 12 – p.3/34

## This Lecture

- Types and type systems
- Language safety
- Achieving safety through types:
  - relating static and dynamic semantics
  - Safety = Progress + Preservation

Much of this lecture follows parts of the first few chapters of B. C. Pierce 2002 *Types and Programming Languages* closely.

G54FOP: Lecture 12 – p.2/34

## Types and Type Systems (2)

Notes on the definition:

- **Static (= compile time) checking** implied since the goal is to **prove** absence of certain errors.
- Done by **classifying** syntactic phrases (or **terms**) according to the **kinds** of value they compute: a type system computes a **static approximation** of the run-time behaviour.

G54FOP: Lecture 12 – p.4/34

## Types and Type Systems (3)

Example: if known that two program fragments  $exp_1$  and  $exp_2$  compute integers (**classification**), then it is safe to add those numbers together (**absence of errors**):

$$exp_1 + exp_2$$

Also known that the result is an integer. While not known exactly which integers are involved, at least known they are integers and nothing else (**static approximation**).

G54FOP: Lecture 12 – p.5/34

## Types and Type Systems (5)

- A type system is necessarily **conservative**: some well-behaved programs will be rejected.

For example, typically

*if complex test then S else type error*

will be rejected as ill-typed, even if *complex test* actually always evaluates to true, since that cannot be known statically in general.

G54FOP: Lecture 12 – p.7/34

## Types and Type Systems (4)

- “Dynamically typed” languages do not have a type system according to this definition; they should really be called **dynamically checked**.

Example. In a dynamically checked language,  $exp_1 + exp_2$  would be evaluated as follows:

- Evaluate  $exp_1$  and  $exp_2$
- Add results together in a manner depending on their types (integer addition, floating point addition, . . . ), or signal error if not possible.

G54FOP: Lecture 12 – p.6/34

## Types and Type Systems (6)

- A type system checks for **certain** kinds of bad program behaviour, or **run-time errors**. Exactly which depends on the type system and the language design.

For example: current main-stream type systems typically

**do check** that arithmetic operations only are done on numbers  
**do not check** that the second operand of division is not zero, that array indices are within bounds.

G54FOP: Lecture 12 – p.8/34

## Types and Type Systems (7)

- The **safety** or **soundness** of a type system must be judged with respect to its own set of run-time errors.

G54FOP: Lecture 12 – p.9/34

## Language Safety (2)

- Language safety **not** the same as static typing: safety can be **achieved** through static typing and/or dynamic run-time checks.
- Scheme is a dynamically checked safe language.
- Even statically typed languages usually use some dynamic checks; e.g.:
  - checking of array bounds
  - down-casting (e.g. Java)
  - checking for division by zero
  - pattern-matching failure

G54FOP: Lecture 12 – p.11/34

## Language Safety (1)

Language safety is a contentious notion. A possible definition (Pierce):

*A safe language is one that protects its own abstractions.*

For example: a Java object should behave as an object; e.g. it would be bad if it was destroyed by creation of some **other** object.

Other examples: lexical scope rules, visibility attributes (`public`, `protected`, ...).

G54FOP: Lecture 12 – p.10/34

## Language Safety (3)

Some examples of statically and dynamically checked safe and unsafe high-level languages:

|        | Statically chkd   | Dynamically chkd                       |
|--------|-------------------|--|
| Safe   | ML, Haskell, Java | Lisp, Scheme, Perl, Python, Postscript |
| Unsafe | C, C++            | Certain Basic dialects                 |

G54FOP: Lecture 12 – p.12/34

## Static and Dynamic Semantics

In summary:

- A type system *statically* proves properties about the *dynamic* behaviour of a programs.
- To make precise exactly what these properties are, and formally *prove* that a type system achieves its goals, both the
  - *static semantics*
  - *dynamic semantics*
 must first be formalized.

G54FOP: Lecture 12 – p.13/34

## Example Language: Abstract Syntax

Example language. (Will be extended later.)

|                 |                           |                       |
|-----------------|---------------------------|-----------------------|
| $t \rightarrow$ |                           | <i>terms:</i>         |
|                 | <b>true</b>               | <i>constant true</i>  |
|                 | <b>false</b>              | <i>constant false</i> |
|                 | <b>if t then t else t</b> | <i>conditional</i>    |
|                 | <b>0</b>                  | <i>constant zero</i>  |
|                 | <b>succ t</b>             | <i>successor</i>      |
|                 | <b>pred t</b>             | <i>predecessor</i>    |
|                 | <b>iszero t</b>           | <i>zero test</i>      |

G54FOP: Lecture 12 – p.14/34

## Values

|                 |              |                      |
|-----------------|--------------|----------------------|
| $v \rightarrow$ |              | <i>values:</i>       |
|                 | <b>true</b>  | <i>true value</i>    |
|                 | <b>false</b> | <i>false value</i>   |
|                 | <i>nv</i>    | <i>numeric value</i> |

|                  |                |                        |
|------------------|----------------|------------------------|
| $nv \rightarrow$ |                | <i>numeric values:</i> |
|                  | <b>0</b>       | <i>zero value</i>      |
|                  | <b>succ nv</b> | <i>successor value</i> |

Recall: all values are *normal forms*.

G54FOP: Lecture 12 – p.15/34

## Dynamic Semantics (1)

We will define the dynamic semantics *operationally* by giving a (small step) evaluation relation:

$t \longrightarrow t'$       Read:  $t$  evaluates to  $t'$  in one step

**if true then  $t_2$  else  $t_3$**   $\longrightarrow t_2$       (E-IFTRUE)

**if false then  $t_2$  else  $t_3$**   $\longrightarrow t_3$       (E-IFFALSE)

$$\frac{t_1 \longrightarrow t'_1}{\mathbf{if } t_1 \mathbf{ then } t_2 \mathbf{ else } t_3 \longrightarrow \mathbf{if } t'_1 \mathbf{ then } t_2 \mathbf{ else } t_3} \quad (\text{E-IF})$$

G54FOP: Lecture 12 – p.16/34

## Dynamic Semantics (2)

$$\frac{t_1 \longrightarrow t'_1}{\text{succ } t_1 \longrightarrow \text{succ } t'_1} \quad (\text{E-SUCC})$$

$$\text{pred } 0 \longrightarrow 0 \quad (\text{E-PREDZERO})$$

$$\text{pred } (\text{succ } nv_1) \longrightarrow nv_1 \quad (\text{E-PREDSUCC})$$

$$\frac{t_1 \longrightarrow t'_1}{\text{pred } t_1 \longrightarrow \text{pred } t'_1} \quad (\text{E-PRED})$$

G54FOP: Lecture 12 – p.17/34

## Stuck Terms

- Recall that values are normal forms and cannot be evaluated further; for example:
  - `true`
  - `succ (succ 0)`
- However, **all normal forms are not values!**  
Can you find an example?

`if 0 then pred 0 else 0`

Normal forms that are not values are called **stuck terms**.

G54FOP: Lecture 12 – p.19/34

## Dynamic Semantics (3)

$$\text{iszero } 0 \longrightarrow \text{true} \quad (\text{E-ISZEROZERO})$$

$$\text{iszero } (\text{succ } nv_1) \longrightarrow \text{false} \quad (\text{E-ISZEROSUCC})$$

$$\frac{t_1 \longrightarrow t'_1}{\text{iszero } t_1 \longrightarrow \text{iszero } t'_1} \quad (\text{E-ISZERO})$$

G54FOP: Lecture 12 – p.18/34

## Stuckness and Run-Time Errors

- Why stuck?
  - A stuck term is **nonsensical** according to the dynamic semantics.
  - We are attempting to **break the abstractions** of the language.
- We let the notion of getting stuck **model run-time errors**.
- The **goal** of a type system is to rule out **all** ill-defined programs, thus **guaranteeing** that a “good”, i.e., **well-typed**, program **never gets stuck!**

G54FOP: Lecture 12 – p.20/34

## Aside: Curry vs. Church Style

This is the “Curry-style” approach: the dynamic semantics comes before the static semantics.

Alternatively, one can start with the static semantics, and then only consider the dynamic semantics of well-typed terms: the “Church-style” approach.

## Types

At this point, there are only two types, booleans and the natural numbers:

$$T \rightarrow \begin{array}{l} \text{Bool} \quad \text{type of booleans} \\ | \\ \text{Nat} \quad \text{type of natural numbers} \end{array}$$

G54FOP: Lecture 12 – p.21/34

G54FOP: Lecture 12 – p.22/34

## Typing Rules

$\text{true} : \text{Bool}$  (T-TRUE)

$\text{false} : \text{Bool}$  (T-FALSE)

$\frac{t_1 : \text{Bool} \quad t_2 : T \quad t_3 : T}{\text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T}$  (T-IF)

$0 : \text{Nat}$  (T-ZERO)

$\frac{t_1 : \text{Nat}}{\text{succ } t_1 : \text{Nat}}$  (T-SUCC)

$\frac{t_1 : \text{Nat}}{\text{pred } t_1 : \text{Nat}}$  (T-PRED)

$\frac{t_1 : \text{Nat}}{\text{iszero } t_1 : \text{Bool}}$  (T-ISZERO)

G54FOP: Lecture 12 – p.23/34

## Safety = Progress + Preservation (1)

The most basic property of a type system: **safety**, or “**well typed programs do not go wrong**”, where “wrong” means entering a “stuck state”.

This breaks down into two parts:

- **Progress:** A well-typed term is not stuck.
- **Preservation:** If a well-typed term takes a step of evaluation, then the resulting term is also well-typed. (Aka **Subject Reduction**)

Together, these properties say that a well-typed term can never reach a stuck state during evaluation.

G54FOP: Lecture 12 – p.24/34

## Safety = Progress + Preservation (2)

Formally:

- THEOREM [PROGRESS]: Suppose that  $t$  is a well-typed term (i.e.,  $t : T$ ), then either  $t$  is a value or else there is some  $t'$  with  $t \longrightarrow t'$ .

PROOF: By induction on a derivation of  $t : T$ .

- THEOREM [PRESERVATION]: If  $t : T$  and  $t \longrightarrow t'$  then  $t' : T$ .

PROOF: By induction on a derivation of  $t : T$ .

(Strong form: exact type  $T$  preserved.)

G54FOP: Lecture 12 – p.25/34

## Progress: A Proof Fragment (1)

The relevant **typing** and **evaluation** rules for the case T-IF:

$$\frac{t_1 : \mathbf{Bool} \quad t_2 : T \quad t_3 : T}{\mathbf{if} \ t_1 \ \mathbf{then} \ t_2 \ \mathbf{else} \ t_3 : T} \quad (\text{T-IF})$$

$$\mathbf{if} \ \mathbf{true} \ \mathbf{then} \ t_2 \ \mathbf{else} \ t_3 \longrightarrow t_2 \quad (\text{E-IFTRUE})$$

$$\mathbf{if} \ \mathbf{false} \ \mathbf{then} \ t_2 \ \mathbf{else} \ t_3 \longrightarrow t_3 \quad (\text{E-IFFALSE})$$

$$\frac{t_1 \longrightarrow t'_1}{\mathbf{if} \ t_1 \ \mathbf{then} \ t_2 \ \mathbf{else} \ t_3 \longrightarrow \mathbf{if} \ t'_1 \ \mathbf{then} \ t_2 \ \mathbf{else} \ t_3} \quad (\text{E-IF})$$

G54FOP: Lecture 12 – p.26/34

## Progress: A Proof Fragment (2)

A typical case when proving Progress by induction on a derivation of  $t : T$ .

$$\text{Case T-IF: } t = \mathbf{if} \ t_1 \ \mathbf{then} \ t_2 \ \mathbf{else} \ t_3 \\ t_1 : \mathbf{Bool} \quad t_2 : T \quad t_3 : T$$

By ind. hyp, either  $t_1$  is a value, or else there is some  $t'_1$  such that  $t_1 \longrightarrow t'_1$ . If  $t_1$  is a value, then it must be either **true** or **false**, in which case either E-IFTRUE or E-IFFALSE applies to  $t$ . On the other hand, if  $t_1 \longrightarrow t'_1$ , then by E-IF,  $t \longrightarrow \mathbf{if} \ t'_1 \ \mathbf{then} \ t_2 \ \mathbf{else} \ t_3$ .

G54FOP: Lecture 12 – p.27/34

## Preservation: A Proof Fragment (1)

A typical case when proving Preservation by induction on a derivation of  $t : T$ .

$$\text{Case T-IF: } t = \mathbf{if} \ t_1 \ \mathbf{then} \ t_2 \ \mathbf{else} \ t_3 \\ t_1 : \mathbf{Bool} \quad t_2 : T \quad t_3 : T$$

Evaluation can be made by one of the rules E-IFTRUE, E-IFFALSE, E-IF.

If evaluation is by any of the two former, then the result is either  $t_2$  or  $t_3$ . But both have type  $T$ , just like  $t$ , so the type is manifestly preserved.

G54FOP: Lecture 12 – p.28/34

## Preservation: A Proof Fragment (2)

Case T-IF:  $t = \text{if } t_1 \text{ then } t_2 \text{ else } t_3$   
 $t_1 : \text{Bool} \quad t_2 : T \quad t_3 : T$

If evaluation is by rule E-IF, then we know  $t_1 \longrightarrow t'_1$ . Thus, by the induction hypothesis, we know  $t'_1 : \text{Bool}$ . And then we can conclude by T-IF that  $\text{if } t'_1 \text{ then } t_2 \text{ else } t_3 : T$ , so the type is preserved also in this case.

G54FOP: Lecture 12 – p.29/34

## Exceptions (1)

What about terms like

- division by zero
- head of empty list

that usually are considered well-typed?

If the type system does not rule them out, we need to differentiate those from stuck terms, or we can no longer claim that “well-typed programs do not go wrong”!

G54FOP: Lecture 12 – p.31/34

## Homework

1. Prove Progress for the case T-TRUE.
2. Prove Preservation for the case T-TRUE.
3. Prove Progress for the case T-ISZERO.
4. Prove Preservation for the case T-ISZERO.

G54FOP: Lecture 12 – p.30/34

## Exceptions (2)

Idea: allow **exceptions** to be raised, and make it well-defined what happens when exceptions are raised.

For example:

- introduce a term **error**
- introduce evaluation rules like

$\text{head } [] \longrightarrow \text{error}$

- typing rule: **error** :  $T$

G54FOP: Lecture 12 – p.32/34



## Exceptions (3)

- introduce propagation rules to ensure that the entire program evaluates to **error** once the exception has been raised (unless there is some exception handling mechanism), e.g.:

$$\text{pred error} \longrightarrow \text{error}$$

- change the Progress theorem slightly to allow for exceptions:

THEOREM [PROGRESS]: Suppose that  $t$  is a well-typed term (i.e.,  $t : T$ ), then either  $t$  is a value **or error**, or else there is some  $t'$  with  $t \longrightarrow t'$ .

## Aside: **error** is not a value

For technical reasons, to avoid overlap between evaluation rules that propagate error and the normal ones, it can be preferable to not consider **error** a value.

E.g., for function application we might have

$$(\lambda x. t) v \longrightarrow [x \mapsto v]t$$

which would overlap with

$$v \text{ error} \longrightarrow \text{error}$$

if error were considered a value.