

# LiU-FP2010 Part II: Lecture 6

More about Monads and Other Notions of Effectful Computation

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## This Lecture

- Monads in Haskell
- Some standard monads
- Combining effects: monad transformers
- Arrows
- FRP and Yampa

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## Monads in Haskell

In Haskell, the notion of a monad is captured by a **Type Class**:

```
class Monad m where
  return :: a -> m a
  (>>=) :: m a -> (a -> m b) -> m b
```

Allows names of the common functions to be overloaded and sharing of derived definitions.

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## The Maybe Monad in Haskell

```
instance Monad Maybe where
  -- return :: a -> Maybe a
  return = Just

  -- (>>=) :: Maybe a -> (a -> Maybe b)
  --         -> Maybe b
  Nothing >>= _ = Nothing
  (Just x) >>= f = f x
```

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## Exercise 1: A State Monad in Haskell

Haskell 98 does not permit type synonyms to be instances of classes. Hence we have to define a new type:

```
newtype S a = S (Int -> (a, Int))

unS :: S a -> (Int -> (a, Int))
unS (S f) = f
```

Provide a Monad instance for `S`.

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## Exercise 1: Solution

```
instance Monad S where
  return a = S (\s -> (a, s))

  m >>= f = S $ \s ->
    let (a, s') = unS m s
    in unS (f a) s'
```

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## Monad-specific Operations (1)

To be useful, monads need to be equipped with additional operations specific to the effects in question. For example:

```
fail :: String -> Maybe a
fail s = Nothing
```

```
catch :: Maybe a -> Maybe a -> Maybe a
m1 'catch' m2 =
  case m1 of
    Just _ -> m1
    Nothing -> m2
```

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## Monad-specific Operations (2)

Typical operations on a state monad:

```
set :: Int -> S ()
set a = S (\_ -> ((), a))
```

```
get :: S Int
get = S (\s -> (s, s))
```

Moreover, need to “run” a computation. E.g.:

```
runS :: S a -> a
runS m = fst (unS m 0)
```

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## The do-notation (1)

Haskell provides convenient syntax for programming with monads:

```
do
  a <- exp1
  b <- exp2
  return exp3
```

is syntactic sugar for

```
exp1 >>= \a ->
exp2 >>= \b ->
return exp3
```

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## The do-notation (2)

Computations can be done solely for effect, ignoring the computed value:

```
do
  exp1
  exp2
  return exp3
```

is syntactic sugar for

```
exp1 >>= \_ ->
exp2 >>= \_ ->
return exp3
```

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## The do-notation (3)

A let-construct is also provided:

```
do
  let a = exp1
      b = exp2
  return exp3
```

is equivalent to

```
do
  a <- return exp1
  b <- return exp2
  return exp3
```

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## Numbering Trees in do-notation

```
numberTree :: Tree a -> Tree Int
numberTree t = runS (ntAux t)
```

```
where
  ntAux :: Tree a -> S (Tree Int)
  ntAux (Leaf _) = do
    n <- get
    set (n + 1)
    return (Leaf n)
  ntAux (Node t1 t2) = do
    t1' <- ntAux t1
    t2' <- ntAux t2
    return (Node t1' t2')
```

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## The Compiler Fragment Revisited (1)

Given a suitable “Diagnostics” monad  $D$  that collects error messages, `enterVar` can be turned from this:

```
enterVar :: Id -> Int -> Type -> Env
          -> Either Env ErrorMgs
```

into this:

```
enterVarD :: Id -> Int -> Type -> Env
           -> D Env
```

and then `identDefs` from this ...

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## The Compiler Fragment Revisited (2)

```
identDefs l env [] = ([], env, [])
identDefs l env ((i,t,e) : ds) =
  ((i,t,e') : ds', env'', ms1++ms2++ms3)
  where
    (e', ms1) = identAux l env e
    (env', ms2) =
      case enterVar i l t env of
        Left env' -> (env', [])
        Right m -> (env, [m])
    (ds', env'', ms3) =
      identDefs l env' ds
```

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## The Compiler Fragment Revisited (3)

into this:

```
identDefsD l env [] = return ([], env)
identDefsD l env ((i,t,e) : ds) = do
  e' <- identAuxD l env e
  env' <- enterVarD i l t env
  (ds', env'') <- identDefsD l env' ds
  return ((i,t,e') : ds', env'')
```

(Suffix  $D$  just to remind us the types have changed.)

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## The Compiler Fragment Revisited (4)

Compare with the “core” identified earlier!

```
identDefs l env [] = ([], env)
identDefs l env ((i,t,e) : ds) =
  ((i,t,e') : ds', env'')
  where
    e' = identAux l env e
    env' = enterVar i l t env
    (ds', env'') = identDefs l env' ds
```

The monadic version is very close to ideal, without sacrificing functionality, clarity, or pureness!

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## The List Monad

Computation with many possible results, “nondeterminism”:

```
instance Monad [] where
  return a = [a]
  m >>= f = concat (map f m)
  fail s = []
```

Example:

```
x <- [1, 2]
y <- ['a', 'b']
return (x,y)
```

Result:

```
[(1,'a'),(1,'b'),
 (2,'a'),(2,'b')]
```

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## The Reader Monad

Computation in an environment:

```
instance Monad ((->) e) where
  return a = const a
  m >>= f = \e -> f (m e) e
```

```
getEnv :: ((->) e) e
getEnv = id
```

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## The Haskell IO Monad

In Haskell, IO is handled through the IO monad. IO is **abstract**! Conceptually:

```
newtype IO a = IO (World -> (a, World))
```

Some operations:

```
putChar    :: Char -> IO ()
putStr     :: String -> IO ()
putStrLn   :: String -> IO ()
getChar    :: IO Char
getLine    :: IO String
getContent :: String
```

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## Monad Transformers (1)

What if we need to support more than one type of effect?

For example: State and Error/Partiality?

We could implement a suitable monad from scratch:

```
newtype SE s a = SE (s -> Maybe (a, s))
```

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## Monad Transformers (2)

However:

- Not always obvious how: e.g., should the combination of state and error have been  

```
newtype SE s a = SE (s -> (Maybe a, s))
```
- Duplication of effort: similar patterns related to specific effects are going to be repeated over and over in the various combinations.

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## Monad Transformers (3)

**Monad Transformers** can help:

- A **monad transformer** transforms a monad by adding support for an additional effect.
- A library of monad transformers can be developed, each adding a specific effect (state, error, ...), allowing the programmer to mix and match.
- A form of **aspect-oriented programming**.

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## Monad Transformers in Haskell (1)

- A **monad transformer** maps monads to monads. Represented by a type constructor  $T$  of the following kind:

```
T :: (* -> *) -> (* -> *)
```

- Additionally, a monad transformer **adds** computational effects. A mapping **lift** from computations in the underlying monad to computations in the transformed monad is needed:

```
lift :: M a -> T M a
```

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## Monad Transformers in Haskell (2)

- These requirements are captured by the following (multi-parameter) type class:

```
class (Monad m, Monad (t m))
  => MonadTransformer t m where
  lift :: m a -> t m a
```

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## Classes for Specific Effects

A monad transformer adds specific effects to **any** monad. Thus the effect-specific operations needs to be overloaded. For example:

```
class Monad m => E m where
  eFail :: m a
  eHandle :: m a -> m a -> m a

class Monad m => S m s | m -> s where
  sSet :: s -> m ()
  sGet :: m s
```

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## The Identity Monad

We are going to construct monads by successive transformations of the identity monad:

```
newtype I a = I a
unI (I a) = a

instance Monad I where
  return a = I a
  m >>= f = f (unI m)

runI :: I a -> a
runI = unI
```

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## The Error Monad Transformer (1)

```
newtype ET m a = ET (m (Maybe a))
unET (ET m) = m
```

Any monad transformed by ET is a monad:

```
instance Monad m => Monad (ET m) where
  return a = ET (return (Just a))

m >>= f = ET $ do
  ma <- unET m
  case ma of
    Nothing -> return Nothing
    Just a -> unET (f a)
```

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## The Error Monad Transformer (2)

We need the ability to run transformed monads:

```
runET :: Monad m => ET m a -> m a
runET etm = do
  ma <- unET etm
  case ma of
    Just a   -> return a
    Nothing  -> error "Should not happen"
```

ET is a monad transformer:

```
instance Monad m =>
  MonadTransformer ET m where
  lift m = ET (m >>= \a -> return (Just a))
```

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## The Error Monad Transformer (3)

Any monad transformed by ET is an instance of E:

```
instance Monad m => E (ET m) where
  eFail = ET (return Nothing)
  m1 'eHandle' m2 = ET $ do
    ma <- unET m1
    case ma of
      Nothing -> unET m2
      Just _  -> return ma
```

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## The Error Monad Transformer (4)

A state monad transformed by ET is a state monad:

```
instance S m s => S (ET m) s where
  sSet s = lift (sSet s)
  sGet = lift sGet
```

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## Exercise 2: Running Transf. Monads

Let

```
ex2 = eFail 'eHandle' return 1
```

1. Suggest a possible type for ex2. (Assume `1 :: Int`.)
2. Given your type, use the appropriate combination of “run functions” to run ex2.

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## Exercise 2: Solution

```
ex2 :: ET I Int
ex2 = eFail 'eHandle' return 1

ex2result :: Int
ex2result = runI (runET ex2)
```

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## The State Monad Transformer (1)

```
newtype ST s m a = ST (s -> m (a, s))
unST (ST m) = m
```

Any monad transformed by ST is a monad:

```
instance Monad m => Monad (ST s m) where
  return a = ST (\s -> return (a, s))

m >>= f = ST $ \s -> do
  (a, s') <- unST m s
  unST (f a) s'
```

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## The State Monad Transformer (2)

We need the ability to run transformed monads:

```
runST :: Monad m => ST s m a -> s -> m a
runST stf s0 = do
  (a, _) <- unST stf s0
  return a
```

ST is a monad transformer:

```
instance Monad m =>
  MonadTransformer (ST s) m where
  lift m = ST (\s -> m >>= \a ->
    return (a, s))
```

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## The State Monad Transformer (3)

Any monad transformed by ST is an instance of S:

```
instance Monad m => S (ST s m) s where
  sSet s = ST (\_ -> return ((, s)))
  sGet = ST (\s -> return (s, s))
```

An error monad transformed by ST is an error monad:

```
instance E m => E (ST s m) where
  eFail = lift eFail
  m1 'eHandle' m2 = ST $ \s ->
    unST m1 s 'eHandle' unST m2 s
```

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## Exercise 3: Effect Ordering

Consider the code fragment

```
ex3a :: (ST Int (ET I)) Int
ex3a = (sSet 42 >> eFail) 'eHandle' sGet
```

Note that the exact same code fragment also can be typed as follows:

```
ex3b :: (ET (ST Int I)) Int
ex3b = (sSet 42 >> eFail) 'eHandle' sGet
```

What is

```
runI (runET (runST ex3a 0))
runI (runST (runET ex3b) 0)
```

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## Exercise 3: Solution

```
runI (runET (runST ex3a 0)) = 0
runI (runST (runET ex3b) 0) = 24
```

Why? Because:

```
ST s (ET I) a ≈ s -> (ET I) (a, s)
              ≈ s -> I (Maybe (a, s))
              ≈ s -> Maybe (a, s)
ET (ST s I) a ≈ (ST s I) (Maybe a)
              ≈ s -> I (Maybe a, s)
              ≈ s -> (Maybe a, s)
```

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## Exercise 4: Alternative ST?

To think about.

Could ST have been defined in some other way, e.g.

```
newtype ST s m a = ST (m (s -> (a, s)))
```

or perhaps

```
newtype ST s m a = ST (s -> (m a, s))
```

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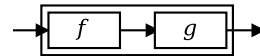
## Problems with Monad Transformers

- With one transformer for each possible effect, we get a lot of combinations: the number grows quadratically; each has to be instantiated explicitly.
- Jaskelioff (2008,2009) has proposed a possible, more extensible alternative.

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## Arrows (1)

System descriptions in the form of block diagrams are very common. Blocks have inputs and outputs and can be combined into larger blocks. For example, serial composition:



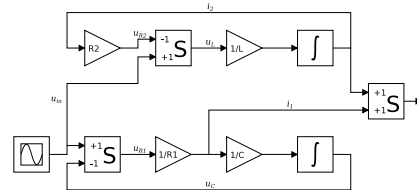
A *combinator* can be defined that captures this idea:

```
(>>>) :: B a b -> B b c -> B a c
```

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## Arrows (2)

But systems can be complex:



**How many and what combinators do we need to be able to describe arbitrary systems?**

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## Arrows (3)

John Hughes' **arrow** framework:

- Abstract data type interface for function-like types (or “blocks”, if you prefer).
- Particularly suitable for types representing process-like computations.
- Related to **monads**, since arrows are computations, but more general.
- Provides a minimal set of “wiring” combinators.

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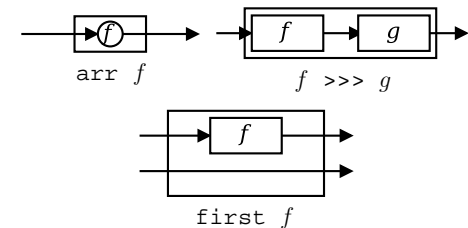
## What is an arrow? (1)

- A **type constructor**  $a$  of arity two.
- Three operators:
  - **lifting**:  
 $\text{arr} :: (b \rightarrow c) \rightarrow a\ b\ c$
  - **composition**:  
 $(\gg\gg) :: a\ b\ c \rightarrow a\ c\ d \rightarrow a\ b\ d$
  - **widening**:  
 $\text{first} :: a\ b\ c \rightarrow a\ (b,d)\ (c,d)$
- A set of **algebraic laws** that must hold.

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## What is an arrow? (2)

These diagrams convey the general idea:



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## The Arrow class

In Haskell, a **type class** is used to capture these ideas (except for the laws):

```
class Arrow a where
  arr    :: (b -> c) -> a b c
  (>>>) :: a b c -> a c d -> a b d
  first  :: a b c -> a (b,d) (c,d)
```

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## Functions are arrows (1)

Functions are a simple example of arrows, with `(->)` as the arrow type constructor.

**Exercise 5:** Suggest suitable definitions of

- `arr`
- `(>>>)`
- `first`

for this case!

(We have not looked at what the laws are yet, but they are “natural”.)

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## Functions are arrows (2)

Solution:

- `arr = id`  
To see this, recall  
`id :: t -> t`  
`arr :: (b->c) -> a b c`

Instantiate with

```
a = (->)
t = b->c = (->) b c
```

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## Functions are arrows (3)

- `f >>> g = \a -> g (f a)` **or**
- `f >>> g = g . f` **or even**
- `(>>>) = flip (.)`
- `first f = \ (b,d) -> (f b,d)`

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## Functions are arrows (4)

Arrow instance declaration for functions:

```
instance Arrow (->) where
  arr      = id
  (>>>)    = flip (.)
  first f  = \ (b,d) -> (f b,d)
```

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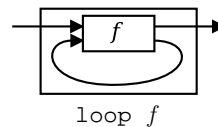
## Some arrow laws

```
(f >>> g) >>> h = f >>> (g >>> h)
arr (f >>> g) = arr f >>> arr g
arr id >>> f = f
              f = f >>> arr id
first (arr f) = arr (first f)
first (f >>> g) = first f >>> first g
```

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## The loop combinator (1)

Another important operator is `loop`: a fixed-point operator used to express recursive arrows or **feedback**:



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## The loop combinator (2)

Not all arrow instances support `loop`. It is thus a method of a separate class:

```
class Arrow a => ArrowLoop a where
  loop :: a (b, d) (c, d) -> a b c
```

Remarkably, the four combinators `arr`, `>>>`, `first`, and `loop` are sufficient to express any conceivable wiring!

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## Some more arrow combinators (1)

```
second :: Arrow a =>
  a b c -> a (d,b) (d,c)
```

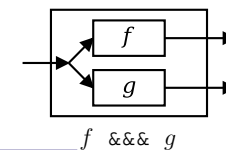
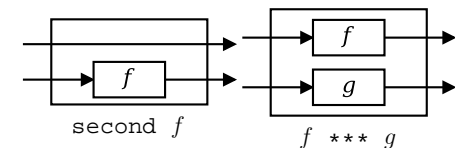
```
(***) :: Arrow a =>
  a b c -> a d e -> a (b,d) (c,e)
```

```
(&&&) :: Arrow a =>
  a b c -> a b d -> a b (c,d)
```

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## Some more arrow combinators (2)

As diagrams:



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## Some more arrow combinators (3)

```
second :: Arrow a => a b c -> a (d,b) (d,c)
second f = arr swap >>> first f >>> arr swap
swap (x,y) = (y,x)

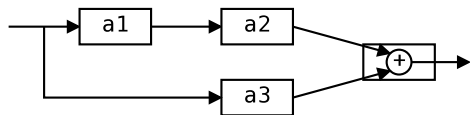
(***) :: Arrow a =>
  a b c -> a d e -> a (b,d) (c,e)
f *** g = first f >>> second g

(&&&) :: Arrow a => a b c -> a b d -> a b (c,d)
f &&& g = arr (\x->(x,x)) >>> (f *** g)
```

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## Exercise 6

Describe the following circuit using arrow combinators:

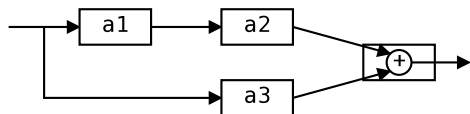


a1, a2, a3 :: A Double Double

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## Exercise 6: One solution

**Exercise 3:** Describe the following circuit using arrow combinators:



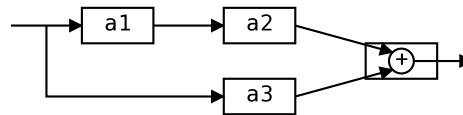
a1, a2, a3 :: A Double Double

```
circuit_v1 :: A Double Double
circuit_v1 = (a1 &&& arr id)
  >>> (a2 *** a3)
  >>> arr (uncurry (+))
```

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## Exercise 6: Another solution

**Exercise 3:** Describe the following circuit:



a1, a2, a3 :: A Double Double

```
circuit_v2 :: A Double Double
circuit_v2 = arr (\x -> (x,x))
  >>> first a1
  >>> (a2 *** a3)
  >>> arr (uncurry (+))
```

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## The arrow do notation (1)

Ross Paterson's *do*-notation for arrows supports **pointed** arrow programming. Only **syntactic sugar**.

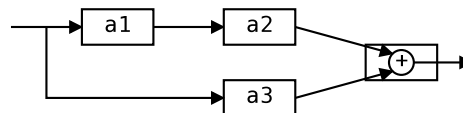
```
proc pat -> do [ rec ]
  pat1 <- sfexp1 -< exp1
  pat2 <- sfexp2 -< exp2
  ...
  patn <- sfexpn -< expn
  returnA -< exp
```

Also: let *pat* = *exp* ≡ *pat* <- arr id -< *exp*

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## The arrow do notation (2)

Let us redo exercise 3 using this notation:



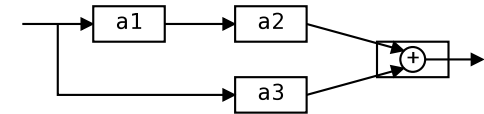
circuit\_v4 :: A Double Double

```
circuit_v4 = proc x -> do
  y1 <- a1 -< x
  y2 <- a2 -< y1
  y3 <- a3 -< x
  returnA -< y2 + y3
```

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## The arrow do notation (3)

We can also mix and match:



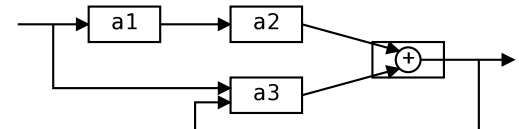
circuit\_v5 :: A Double Double

```
circuit_v5 = proc x -> do
  y2 <- a2 <<< a1 -< x
  y3 <- a3 -< x
  returnA -< y2 + y3
```

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## The arrow do notation (4)

Recursive networks: *do*-notation:



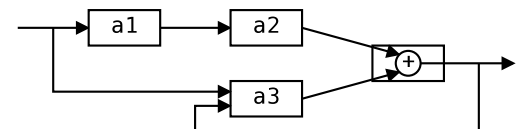
a1, a2 :: A Double Double

a3 :: A (Double,Double) Double

**Exercise 5:** Describe this using only the arrow combinators.

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## The arrow do notation (5)



```
circuit = proc x -> do
  rec
  y1 <- a1 -< x
  y2 <- a2 -< y1
  y3 <- a3 -< (x, y)
  let y = y2 + y3
  returnA -< y
```

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## Arrows and Monads (1)

Arrows generalize monads: for every monad type there is an arrow, the **Kleisli category** for the monad:

```
newtype Kleisli m a b = K (a -> m b)

instance Monad m => Arrow (Kleisli m) where
  arr f      = K (\b -> return (f b))
  K f >>> K g = K (\b -> f b >>= g)
```

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## Arrows and Monads (2)

But not every arrow is a monad. However, arrows that support an additional `apply` operation **are** effectively monads:

```
apply :: Arrow a => a (a b c, b) c
```

Exercise 7: Verify that

```
newtype M b = M (A () b)
```

is a monad if `A` is an arrow supporting `apply`; i.e., define `return` and `bind` in terms of the arrow operations (and verify that the monad laws hold).

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## An application: FRP

Functional Reactive Programming (FRP):

- Paradigm for **reactive programming** in a functional setting:
  - Input arrives **incrementally** while system is running.
  - Output is generated in response to input in an interleaved and **timely** fashion.
- Originated from Functional Reactive Animation (Fran) (Elliott & Hudak).
- Has evolved in a number of directions and into different concrete implementations.

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## Yampa

**Yampa:**

- The most recent Yale FRP implementation.
- Embedding** in Haskell (a Haskell library).
- Arrows** used as the basic structuring framework.
- Continuous time.**
- Discrete-time signals modelled by continuous-time signals and an option type.
- Advanced **switching constructs** allows for highly dynamic system structure.

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## Related languages

FRP related to:

- Synchronous languages, like Esterel, Lucid Synchrone.
- Modeling languages, like Simulink.

Distinguishing features of FRP:

- First class reactive components.
- Allows highly dynamic system structure.
- Supports hybrid (mixed continuous and discrete) systems.

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## FRP applications

Some domains where FRP has been used:

- Graphical Animation (Fran: Elliott, Hudak)
- Robotics (Frob: Peterson, Hager, Hudak, Elliott, Pembeci, Nilsson)
- Vision (FVision: Peterson, Hudak, Reid, Hager)
- GUIs (Fruit: Courtney)
- Hybrid modeling (Nilsson, Hudak, Peterson)

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## Yampa?

Yampa is a river with long calmly flowing sections and abrupt whitewater transitions in between.

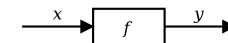


A good metaphor for hybrid systems!

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## Signal functions

Key concept: **functions on signals**.



Intuition:

```
Signal  $\alpha \approx \text{Time} \rightarrow \alpha$ 
 $x :: \text{Signal T1}$ 
 $y :: \text{Signal T2}$ 
 $\text{SF } \alpha \beta \approx \text{Signal } \alpha \rightarrow \text{Signal } \beta$ 
 $f :: \text{SF T1 T2}$ 
```

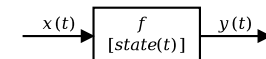
Additionally: **causality** requirement.

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## Signal functions and state

Alternative view:

Signal functions can encapsulate **state**.



$state(t)$  summarizes input history  $x(t')$ ,  $t' \in [0, t]$ .

Functions on signals are either:

- Stateful:**  $y(t)$  depends on  $x(t)$  and  $state(t)$
- Stateless:**  $y(t)$  depends only on  $x(t)$

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## Yampa and Arrows

SF is an arrow. Signal function instances of core combinators:

- `arr :: (a -> b) -> SF a b`
- `>>> :: SF a b -> SF b c -> SF a c`
- `first :: SF a b -> SF (a,c) (b,c)`
- `loop :: SF (a,c) (b,c) -> SF a b`

But `apply` has no useful meaning. Hence SF is **not** a monad.

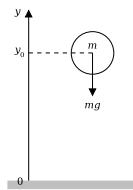
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## Some further basic signal functions

- `identity :: SF a a`  
`identity = arr id`
- `constant :: b -> SF a b`  
`constant b = arr (const b)`
- `integral :: VectorSpace a s=>SF a a`
- `time :: SF a Time`  
`time = constant 1.0 >>> integral`
- `(^<<) :: (b->c) -> SF a b -> SF a c`  
`f (^<<) sf = sf >>> arr f`

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## Example: A bouncing ball



$$y = y_0 + \int v dt$$

$$v = v_0 + \int -9.81$$

On impact:

$$v = -v(t-)$$

(fully elastic collision)

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## Part of a model of the bouncing ball

Free-falling ball:

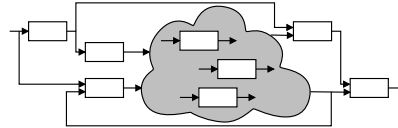
```
type Pos = Double
type Vel = Double
```

```
fallingBall ::
  Pos -> Vel -> SF () (Pos, Vel)
fallingBall y0 v0 = proc () -> do
  v <- (v0 +) ^<< integral <- 9.81
  y <- (y0 +) ^<< integral <- v
  returnA <- (y, v)
```

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## Dynamic system structure

**Switching** allows the structure of the system to evolve over time:



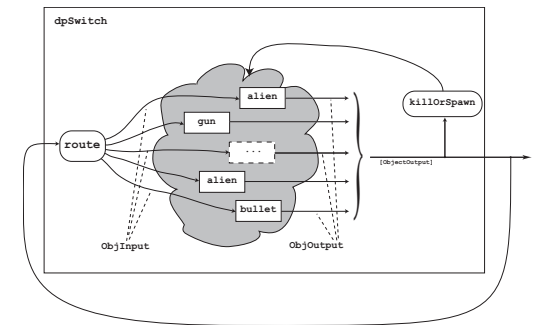
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## Example: Space Invaders



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## Overall game structure



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## Reading (1)

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- Sheng Liang, Paul Hudak, Mark Jones. Monad Transformers and Modular Interpreters. In *Proceedings of the 22nd ACM Symposium on Principles of Programming Languages (POPL'95)*, January 1995, San Francisco, California

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## Reading (2)

- Mauro Jaskelioff. Monatron: An Extensible Monad Transformer Library. In *Implementation of Functional Languages (IFL'08)*, 2008.
- Mauro Jaskelioff. Modular Monad Transformers. In *European Symposium on Programming (ESOP'09)*, 2009.

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## Reading (3)

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- John Hughes. Programming with arrows. In *Advanced Functional Programming*, 2004. To be published by Springer Verlag.
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## Reading (4)

- Paul Hudak, Antony Courtney, Henrik Nilsson, and John Peterson. Arrows, robots, and functional reactive programming. In *Advanced Functional Programming*, 2002. LNCS 2638, pp. 159–187.
- Antony Courtney, Henrik Nilsson, and John Peterson. The Yampa Arcade. In *Proceedings of the 2003 ACM SIGPLAN Haskell Workshop (Haskell'03)*, Uppsala, Sweden, 2003, pp 7–18.