## This Lecture

## G53CMP: Lecture 15

Run-Time Organization II
Henrik Nilsson

University of Nottingham, UK

Data Representation: how to store various kinds of data.

- General issues
- Primitive types
- Record types
- Arrays
- Disjoint unions
- Recursive types


## G55CMP: Lecture $15-$ - .233 <br> Data Representation: Issues (1)

- Nonconfusion: Different values of a given type must have different representations.
- Uniqueness: Each value should have exactly one representation.
[Note: The discussion concerns run-time representation. Any value that is known statically potentially need no run-time representation at all.]
- We need to encode the data to be stored.


## Nonconfusion (1)

Self-evident: if two different values are represented the same way, they cannot be told apart.

- Dynamically checked language: Every possible value must have a distinct representation.
- (Statically) typed language: Values of the same type must have distinct representations; the same representation may be reused for values of different types.


Example: Consider two enumeration types:

```
data Colour = Red | Green
data Size = Small | Large
```

It must always be the case that

$$
\begin{aligned}
\operatorname{repr}(\text { Red }) & \neq \operatorname{repr}(\text { Green }) \\
\operatorname{repr}(\text { Small }) & \neq \operatorname{repr}(\text { Large })
\end{aligned}
$$

Further, in a dynamically checked setting:

$$
\begin{aligned}
\{\operatorname{repr}(\text { Red }), \operatorname{repr}(\text { Green })\} & \cap\{\operatorname{repr}(\text { Small }), \text { repr }(\text { Large })\} \\
& =\emptyset
\end{aligned}
$$

## Nonconfusion (2)

Example: suppose both characters and small integers represented by 8 -bit bytes:

- $\operatorname{repr}\left({ }^{\prime} \mathrm{A}^{\prime}\right)=01000001$
- $\operatorname{repr}(65)=01000001$

Suppose a variable x contains this value 01000001 :
Should print (x) print ' $\mathrm{A}^{\prime}$ or 65?

- No way to tell the representation of ' ${ }_{A}{ }^{\prime}$ and 65 apart in a dynamically checked setting.
- In a statically typed setting, the type is used to disambiguate.


## Uniqueness

Comparison of values is facilitated if each value has exactly one representation.

However, not essential. One exception:

- Floating-point representations typically have a separate sign bit. Thus, the representation of +0 is distinct from the representation of -0 .


## Data Representation: Issues (2)

- Constant-size representation: The representations of all values of a given type occupy the same amount of space.
- Direct or iindirect (via pointer) representation.

Constant-size representation enables compiler to statically plan storage allocation (since type and hence size is known statically).
If not possible/too wasteful: use some form of indirect representation.

## Direct or Indirect Representation (2)

- Pros direct representation:
- efficient access
- no heap allocation/deallocation overhead
- Pros indirect representation:
- supports varying size data (like dynamic arrays)
- supports recursive types (like linked lists, trees)
- facilitates implementation of parametric polymorphism (as handles can be uniform)


## Direct or Indirect Representation (1)

- Direct representation: the representation of a value $x$ is the binary representation of $x$ :

```
repr. \(x\)
```

- Indirect representation: $x$ represented by a handle that points to a binary representation of $x$ (on the stack or in the heap):



## Representing Primitive Types (1)

Primitive types are often supported directly by the underlying hardware. For example, a 32-bit machine might support:

- addressing of 8-bit bytes and 32-bit words
- 32-bit twos-complement integer arithmetic
- 64-bit floating point operations

There are also standard encoding conventions, such as the 7-bit ASCII or 8-bit ISO character codes, or the Unicode standard. Adopting such conventions facilitates interoperability and communication.

## Representing Primitive Types (2)

On such a 32-bit machine, the following is a possible representation choice:

| Type | Representation | Size |
| :--- | :--- | :--- |
| Boolean | 0 for false; 1 for true | 8-bit byte |
| Char | ISO Latin 1 encoding | 8-bit byte |
| Integer | twos-complement repr. | 32-bit word |
| Real | floating point repr. | 64-bit word |



Representation of records:

- Sequence of representations of individual fields.
- Caveat: alignment restrictions. The underlying architecture might require that e.g. word-sized quantities start at a word boundary.
- Relaxing this is possible, but may require extra work; e.g., accessing a word byte by byte (four instructions instead of one).


## Representing Records (1)

A record consists of several fields, each of which has an identifier. For example:

```
type Date = record
    : Integer,
    m: Integer,
    d: Integer
    end;
type Details = record
female: Boolean,
dob: Date,
status: Char
```


## Alignment

- An address $a$ is $n$-byte aligned iff $a \equiv 0(\bmod n)$.
- A variable/field etc. is $n$-byte aligned iff it is stored starting at an $n$-byte aligned address.
- To satisfy alignment requirements of its components, a variable of aggregate type like a record is commonly aligned according to the maximum alignment of its components.
- Padding may be needed between variables/ components to ensure the alignment requirements of each is met.


## Exercise: Representing Records (1)

## Assume:

- 1 word $=4$ byte $=32$ bit Integers
- 1 byte $=8$ bit Boolean and Char
- Integer must be word aligned

What is the alignment and size of the type Date?

```
type Date = record
    y: Integer,
    m: Integer,
    d: Integer
end;
```


## Exercise: Representing Records (3)

Size of Date is 3 32-bit words, size of Details is $1+3+1=532$-bit words:


## Exercise: Representing Records (2)

What is the alignment and size of the type Details?

```
type Details = record
```

female: Boolean,
dob: Date,
status: Char
;

Given a variable x : Details, what are the addresses of $x . f e m a l e, x . d o b . y, x . d o b . m$, x.dob.d, x.status relative to $\operatorname{addr}(\mathrm{x})$ ?


Consider the following MiniTriangle program and the resulting (unoptimized) TAM code:

| let var $r:$ | LOADLB | 0 | 3 |
| :---: | :--- | :--- | :--- |
|  | $\{\mathrm{a}:$ Integer, | LOADL | 1 |
|  | $\mathrm{~b}:$ Boolean, | LOADA | $[S B+0]$ |
|  | $\mathrm{c}:$ Integer $\}$ | LOADL | 1 |
| in |  | ADD |  |
|  | r.b $:=$ true | STOREIB | 1 |
|  |  | POP | 0 |
|  |  | HALT |  |

## Record Field Order

The order of the fields in the representation of a record need not be the same as at the source level:

- Fields could be reordered to attempt to reduce waste of space due to alignment restrictions.
- The language design might stipulate that a record is a set of named fields; i.e., their order is irrelevant.

MiniTriangle adopts the set view (and HMTC orders fields alphabetically in a record representation).

## Representing Arrays (2)

Static array: required storage space and array bounds known at compile time. Consider:

```
var x : T[n]
```

- Required storage: $n \times \operatorname{sizeof}(T)$
- Access of $\mathrm{x}[i]$ :
- Verify that $0 \leq i \leq(n-1)$
- Compute address $a$ of desired element:

$$
a=\operatorname{addr}(\mathrm{x}[0])+\mathrm{i} \times \operatorname{sizeof}(T)
$$

- Fetch/store value at address $a$.


## Representing Arrays (1)

- Array represented by sequence of representations of individual array elements.
- Two cases:
- Static Array: Number of elements known at compile time.
- Dynamic Array: Number of elements determined at run time.
- When accessing array elements, must ensure indices are within bounds.
- Address of element computed from base address of array, index, and size of elements.


## Representing Arrays (3)

| Example: TAM code for a [3] := 7 given |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| var a: I | Integer[ |  | (at [SB + | + 0]) |
| LOADL | 7 |  | LSS |  |
| LOADA | [SB + 0] |  | JUMP IFNZ | \#1 |
| LOADL | 3 | \#0: | CALL | ixerror |
| LOAD | [ST - 1] | \#1: | LOADL | 1 |
| LOADL | 0 |  | MUL |  |
| LSS |  |  | ADD |  |
| JUMP IFNZ | \#0 |  | Storei | 0 |
| LOAD | [ST - 1] |  |  |  |
| LOADL | 10 |  |  |  |

## Representing Arrays (4)

- Dynamic array: size of array not known at compile time.
- indirect representation: array accessed via a handle
- handle itself has fixed size
- handle contains pointer to array proper and the array bounds
- storage for array proper allocated at runtime
- index checked by comparing with array bounds stored in the handle.


## Representing Disjoint Unions (2)

- A disjoint union can be represented like a record.
- The value of the tag field determines the layout of the rest of the record.
- If constant size is necessary, size is the maximal size over the various possible layouts.


## Representing Disjoint Unions (1)

- A disjoint union consists of a tag and a variant part.
- The value of the tag determines the type of the variant part.
- Mathematically: $T=T_{1}+\ldots+T_{n}$; given tag $i$, the variant part is a value chosen from type $T_{i}$.
- Disjoint unions occur as
- variant records in Pascal and Ada
- algebraic data types in Haskell and ML
- object types in OO languages like Java, C\#
$\square$


## Representing Disjoint Unions (3)

## Some Haskell Examples:

- data OptInt = NoInt | JustInt Int
- The first tag is No Int; no variant part. (Which is the same as saying that we have a trivial variant part of the unit type ().)
- The second tag is Just Int; the variant part is a single integer field.


## Representing Disjoint Unions (4)

- data Shape
= Triangle Point Point Point
| Rectangle Point Point
| Circle Point Radius
- three tags; the variant parts are:
- Point triple
- Point pair
- Point and Radius pair.
- data Colors = Red | Green | Blue
- three tags; no variant parts.
- this is thus just an enumeration type.


## Uniform Representation (1)

Languages like Haskell and ML adopts a uniform data representation: all values (even "primitive" ones) have an indirect representation (pointer):

- Uniform representation facilitates parametric polymorphism. E.g., the identity function

$$
\text { id } x=x
$$

can be compiled to a single piece of code working for values of any type because all values are represented same way.

- Recursive types supported automatically: "everything is already a pointer".


## Representing Recursive Types

- A recursive type is one defined in terms of itself.
- Examples are linked lists and trees.
- Recursive types are usually represented indirectly since this allows values of arbitrary size to be referenced through a fixed size handle.


## G55CMP: Lecture $15-$-. 30137 <br> Uniform Representation (2)

- Many OO languages, like Java and C\#, adopt a mostly uniform representation:
- All objects are represented by pointers.
- Recursive types thus supported.
- OO-style polymorphism: an object of a class is also an object of any of the superclasses.
- Uniform layout of "common part" of object to allow superclass methods to work on subclass objects.


## Example: Haskell Tree Type (1)

## This example illustrates

- disjoint union representation
- recursive type representation
- uniform representation (through pointers) of values of all types.



## Example: Haskell Tree Type (5)

Of course, the tags (Leaf, Node, and INT) must also be represented. Two possibilities:

- A small integer, subject to nonconfusion. E.g.

$$
\text { Leaf }=0, \text { Node }=1, \text { INT }=0
$$

(Representing both Leaf and Int with the small integer 0 does not lead to confusion in a statically typed language like Haskell.)

- A pointer to an information table.

