G53CMP: Lecture 15 Run-Time Organization II

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Data Representation: Issues (1)

- Nonconfusion: Different values of a given type must have different representations.
- *Uniqueness*: Each value should have exactly one representation.

[Note: The discussion concerns *run-time* representation. Any value that is known *statically* potentially need no run-time representation at all.]

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Nonconfusion (3)

Example: Consider two enumeration types:

data Colour = Red | Green
data Size = Small | Large

It must always be the case that

repr(Red) ≠ repr(Green)
repr(Small) ≠ repr(Large)

Further, in a dynamically checked setting:

 $\begin{aligned} \{ \operatorname{repr}(\texttt{Red}), \operatorname{repr}(\texttt{Green}) \} &\cap \{ \operatorname{repr}(\texttt{Small}), \operatorname{repr}(\texttt{Large}) \} \\ &= \emptyset \end{aligned}$

This Lecture

Data Representation: how to store various kinds of data.

- General issues
- Primitive types
- Record types
- Arrays
- · Disjoint unions
- Recursive types

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Nonconfusion (1)

Self-evident: if two *different* values are represented the *same* way, they cannot be told apart.

- Dynamically checked language: Every possible value must have a distinct representation.
- (Statically) typed language: Values of the same type must have distinct representations; the same representation may be reused for values of different types.

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Uniqueness

Comparison of values is facilitated if each value has exactly one representation.

However, not essential. One exception:

 Floating-point representations typically have a separate sign bit. Thus, the representation of +0 is distinct from the representation of -0.

Data Representation?

- Objective: to store various kinds of data.
 Integers, characters, strings, arrays, trees, . . .
- At our disposal: the memory:

address	contents	
10200008	3E124C21	
1020000C	FE7B3811	
10200010	7A7CBBA3	

We need to encode the data to be stored.

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Nonconfusion (2)

Example: suppose both characters and small integers represented by 8-bit bytes:

- repr('A') = 01000001
- repr(65) = 01000001

Suppose a variable x contains this value 01000001: Should print (x) print 'A' or 65?

- No way to tell the representation of 'A' and 65 apart in a dynamically checked setting.
- In a statically typed setting, the type is used to disambiguate.

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Data Representation: Issues (2)

- Constant-size representation: The representations of all values of a given type occupy the same amount of space.
- **Direct** or **indirect** (via pointer) representation.

Constant-size representation enables compiler to statically plan storage allocation (since type and hence size is known statically).

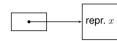
If not possible/too wasteful: use some form of indirect representation.

Direct or Indirect Representation (1)

• *Direct representation*: the representation of a value *x* is the binary representation of *x*:



 Indirect representation: x represented by a handle that points to a binary representation of x (on the stack or in the heap):



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Representing Primitive Types (2)

On such a 32-bit machine, the following is a possible representation choice:

Type	Representation	Size
Boolean	0 for false; 1 for true	8-bit byte
Char	ISO Latin 1 encoding	8-bit byte
Integer	twos-complement repr.	32-bit word
Real floating point repr.		64-bit word

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Alignment

- An address a is n-byte aligned iff $a \equiv 0 \pmod{n}$.
- A variable/field etc. is n-byte aligned iff it is stored starting at an n-byte aligned address.
- To satisfy alignment requirements of its components, a variable of aggregate type like a record is commonly aligned according to the maximum alignment of its components.
- Padding may be needed between variables/ components to ensure the alignment requirements of each is met.

Direct or Indirect Representation (2)

- · Pros direct representation:
 - efficient access
 - no heap allocation/deallocation overhead
- Pros indirect representation:
 - supports varying size data (like dynamic arrays)
 - supports recursive types (like linked lists, trees)
 - facilitates implementation of parametric polymorphism (as handles can be uniform)

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Representing Records (1)

A record consists of several fields, each of which has an identifier. For example:

```
type Date = record
    y: Integer,
    m: Integer,
    d: Integer
end;
type Details = record
    female: Boolean,
    dob: Date,
    status: Char
end;
```

Exercise: Representing Records (1)

Assume:

- 1 word = 4 byte = 32 bit Integers
- 1 byte = 8 bit Boolean and Char
- · Integer must be word aligned

What is the alignment and size of the type Date?

```
type Date = record
    y: Integer,
    m: Integer,
    d: Integer
end;
```

Representing Primitive Types (1)

Primitive types are often supported directly by the underlying hardware. For example, a 32-bit machine might support:

- · addressing of 8-bit bytes and 32-bit words
- · 32-bit twos-complement integer arithmetic
- 64-bit floating point operations

There are also standard encoding conventions, such as the 7-bit ASCII or 8-bit ISO character codes, or the Unicode standard. Adopting such conventions facilitates interoperability and communication.

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Representing Records (2)

Representation of records:

- Sequence of representations of individual fields.
- Caveat: alignment restrictions. The underlying architecture might require that e.g. word-sized quantities start at a word boundary.
- Relaxing this is possible, but may require extra work; e.g., accessing a word byte by byte (four instructions instead of one).

Exercise: Representing Records (2)

What is the alignment and size of the type Details?

Given a variable x: Details, what are the addresses of x.female, x.dob.y, x.dob.m, x.dob.d, x.status relative to $\operatorname{addr}(x)$?

Exercise: Representing Records (3)

Size of Date is 3 32-bit words, size of Details is 1 + 3 + 1 = 5 32-bit words:

variable	address	contents	
x.female	addr(x)	1	(true)
x.dob.y	addr(x) + 4	1984	
x.dob.m	addr(x) + 8	7	
x.dob.d	addr(x) + 12	25	
x.status	addr(x) + 16	117	('u')

Representing Arrays (1)

- Array represented by sequence of representations of individual array elements.
- Two cases:
 - Static Array: Number of elements known at compile time.
 - Dynamic Array: Number of elements determined at run time.
- When accessing array elements, must ensure indices are within bounds.
- Address of element computed from base address of array, index, and size of elements.

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Representing Arrays (4)

- Dynamic array: size of array not known at compile time.
 - indirect representation: array accessed via a handle
 - handle itself has fixed size
 - handle contains pointer to array proper and the array bounds
 - storage for array proper allocated at runtime
 - index checked by comparing with array bounds stored in the handle.

Example: Records in MiniTriangle

Consider the following MiniTriangle program and the resulting (unoptimized) TAM code:

```
let var r :
                         LOADLB
                                     0 3
        {a : Integer,
                        LOADL
                                     1
        b : Boolean,
                        LOADA
                                     [SB + 0]
        c : Integer}
                                     1
                        LOADL
in
                         ADD
                        STOREIB
    r.b := true
                                     1
                        POP
                                     0.3
                         HALT
```

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Representing Arrays (2)

Static array: required storage space and array bounds known at compile time. Consider:

- Required storage: $n \times \operatorname{sizeof}(T)$
- Access of x [i]:
 - Verify that $0 \le i \le (n-1)$
 - Compute address \boldsymbol{a} of desired element:

$$a = \operatorname{addr}(x[0]) + i \times \operatorname{sizeof}(T)$$

- Fetch/store value at address a.

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Representing Disjoint Unions (1)

- A disjoint union consists of a tag and a variant part.
- The value of the tag determines the type of the variant part.
- Mathematically: $T = T_1 + \ldots + T_n$; given tag i, the variant part is a value chosen from type T_i .
- Disjoint unions occur as
 - variant records in Pascal and Ada
- algebraic data types in Haskell and ML
- object types in OO languages like Java, C#

Record Field Order

The order of the fields in the representation of a record need not be the same as at the source level:

- Fields could be reordered to attempt to reduce waste of space due to alignment restrictions.
- The language design might stipulate that a record is a set of named fields; i.e., their order is irrelevant.

MiniTriangle adopts the set view (and HMTC orders fields alphabetically in a record representation).

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Representing Arrays (3)

Example: TAM code for a [3] := 7 given

```
var a: Integer[10] (at [SB + 0])
 LOADL
                        LSS
 LOADA
         [SB + 0]
                        JUMPIFNZ #1
 LOADL
         3
                    #0: CALL
                                ixerror
 LOAD
         [ST - 1] #1: LOADL
 LOADL
         0
                       MUL
 LSS
                       ADD
 JUMPIFNZ #0
                       STOREI 0
 LOAD
         [ST - 1]
         10
 LOADL
```

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Representing Disjoint Unions (2)

- A disjoint union can be represented like a record.
- The value of the tag field determines the layout of the rest of the record.
- If constant size is necessary, size is the maximal size over the various possible layouts.

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Representing Disjoint Unions (3)

Some Haskell Examples:

- data OptInt = NoInt | JustInt Int
 - The first tag is NoInt; no variant part. (Which is the same as saving that we have a trivial variant part of the unit type ().)
 - The second tag is JustInt: the variant part is a single integer field.

Uniform Representation (1)

Languages like Haskell and ML adopts a *uniform* data representation: all values (even "primitive" ones) have an indirect representation (pointer):

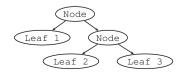
• Uniform representation facilitates *parametric* polymorphism. E.g., the identity function

id x = x

can be compiled to a single piece of code working for values of any type because all values are represented same way.

 Recursive types supported automatically: "everything is already a pointer".

Example: Haskell Tree Type (2)



Representing Disjoint Unions (4)

- · data Shape
 - = Triangle Point Point Point | Rectangle Point Point
 - | Circle Point Radius

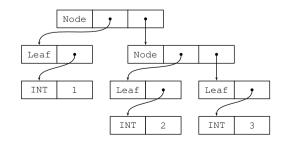
 - three tags; the variant parts are:
 - Point triple
 - Point pair
 - Point and Radius pair.
- data Colors = Red | Green | Blue
 - three tags; no variant parts.
 - this is thus just an enumeration type.

Uniform Representation (2)

- Many OO languages, like Java and C#, adopt a mostly uniform representation:
 - All *objects* are represented by pointers.
 - Recursive types thus supported.
 - OO-style polymorphism: an object of a class is also an object of any of the superclasses.
 - Uniform layout of "common part" of object to allow superclass methods to work on subclass objects.

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Example: Haskell Tree Type (3)



Representing Recursive Types

- A recursive type is one defined in terms of itself.
- Examples are linked lists and trees.
- Recursive types are usually represented indirectly since this allows values of arbitrary size to be referenced through a fixed size handle.

Example: Haskell Tree Type (1)

This example illustrates

- · disjoint union representation
- recursive type representation
- uniform representation (through pointers) of values of all types.

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Example: Haskell Tree Type (4)

address	contents	address	contents
10200008	INT	2E4D0200	Node
1020000C	1	2E4D0204	2E4D0100
10200010	INT	2E4D0208	2E4D0108
10200014	2	2E4D020C	Leaf
		2E4D0210	10200008
2E4D0100	Leaf	2E4D0214	Node
2E4D0104	10200010	2E4D0218	2E4D020C
2E4D0108	Leaf	2E4D021C	2E4D0200
2E4D010C	10200018		
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Example: Haskell Tree Type (5)

Of course, the tags (Leaf, Node, and INT) must also be represented. Two possibilities:

• A small integer, subject to nonconfusion. E.g.

$$\mathtt{Leaf} = 0, \, \mathtt{Node} = 1, \, \mathtt{INT} = 0$$

(Representing both Leaf and INT with the small integer 0 does not lead to confusion in a statically typed language like Haskell.)

• A pointer to an information table.

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