

G53CMP: Lectures 17 & 18

Register Allocation

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- We have seen code generation for TAM, a simple **stack machine**:
 - All instructions target a stack.
 - A few **dedicated** registers (e.g., SB, LB, ST).
 - Register allocation thus a non-issue: allocation decided once and for all by the **design** of the TAM.

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 - Additionally, instructions for **memory access**.
 - Stacks are **implemented** using memory, registers, and memory access instructions.

• ...

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 - ...
 - Very few registers, typically 8–32 word-sized ones, or 32–128 **bytes** of memory.
 - Cf. modern programs that often use **hundreds of Megabytes** of memory.
 - Additionally, registers may be:
 - general purpose
 - special purpose

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- On the other hand:
 - **Have** to use **some** registers because of the way the instruction set is designed.
 - **Want** to use as **many** registers as possible because registers are very fast.
 - **Preferable** to use registers for **frequently** used data over seldomly used data.

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- minimise the memory traffic (loads and stores) by using registers
- subject to:
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 - additional constraints imposed by some registers having a special purpose or not being fully general.

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Again, “optimization”/”minimisation” not used in strict mathematical sense, but in relation to assumed “average” case.

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 - add R_i, R_j, R_k $(R_i := R_j + R_k)$

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- Displacement/offset d in **bytes**.

Exercise: RM Code Generation (1)

Given:

- | Variable | Address |
|----------|---------|
| x | SB + 0 |
| y | SB + 4 |
| z | SB + 8 |

- general purpose registers R0, R1, ... R9

generate code for

$$z := z * (x + y)$$

Exercise: RM Code Generation (2)

One possible answer:

```
load  R0, [SB + 0] ; x
load  R1, [SB + 4] ; y
add   R2, R0, R1
load  R3, [SB + 8] ; z
mul   R4, R3, R2
store R4, [SB + 8] ; z
```

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load  R3, [SB + 8] ; z
mul   R4, R3, R2
store R4, [SB + 8] ; z
```

What if there were fewer registers available?
How many do you need?

Exercise: RM Code Generation (3)

Another possibility using only R0 and R1:

```
load  R0, [SB + 0] ; x
load  R1, [SB + 4] ; y
add   R0, R0, R1
load  R1, [SB + 8] ; z
mul   R1, R1, R0
store R1, [SB + 8] ; z
```

Stack Frame or Activation Record

address	contents
LB - <i>argOffset</i>	arguments
...	...
LB	static link
LB + 4	dynamic link
LB + 8	return address
LB + 12	local variables
...	...
LB + <i>tempOffset</i>	temporary storage

where

$$argOffset = size(arguments)$$

$$tempOffset = 12 + size(variables)$$

(Offsets in bytes for register machine.)

Register Machine Code Generation (1)

We can implement a code generation function *evaluate* in a similar way to the stack machine code generator, except that it returns the **register** in which the result will be stored.

Assuming a code generation monad CG for keeping track of generated code, free registers, etc., we'd get:

$$evaluate : Expression \rightarrow CG\ Reg$$

(ignoring bookkeeping arguments such as scope level and environment.)

Register Machine Code Generation (2)

Operation for getting a currently free register:

freeReg : CG Reg

In a naive scheme (or as a precursor to a register allocation step), *freeReg* would always return a previously unused register:

```
evaluate  $[[E_1 + E_2]] = \mathbf{do}$   
   $r_1 \leftarrow \text{evaluate } E_1$   
   $r_2 \leftarrow \text{evaluate } E_2$   
   $r \leftarrow \text{freeReg}$   
  emit (Add  $r$   $r_1$   $r_2$ )  
  return  $r$ 
```

Example: A Simple Function

```
var n: Integer;  
...  
fun f(x, y: Integer): Integer =  
  let  
    z: Integer  
  in begin  
    z := x * x + y * y;  
    return n * z  
  end
```

We will consider the body less the details of storage allocation for `z` and `return`.

Naive Register Machine Code

Code for $z := x*x + y*y$; *return* $n*z$:

load R0, [LB - 8] ; *offset*(x) = -8

load R1, [LB - 8]

mul R2, R0, R1 ; $R2 := x^2$

load R3, [LB - 4] ; *offset*(y) = -4

load R4, [LB - 4]

mul R5, R3, R4 ; $R5 := y^2$

add R6, R2, R5 ; $R6 := x^2 + y^2$

store R6, [LB + 12] ; *offset*(z) = 12

load R7, [SB + 168] ; *offset*(n) = 4×42

load R8, [LB + 12]

mul R9, R7, R8 ; $R9 := n(x^2 + y^2)$

Stack Machine Code

TAM-code for the example for comparison:

```
LOAD [LB - 2] ; x      ADD
LOAD [LB - 2] ; x      STORE [LB + 3] ; z
MUL                    LOAD [SB + 42] ; n
LOAD [LB - 1] ; y      LOAD [LB + 3] ; z
LOAD [LB - 1] ; y      MUL
MUL
```

Note: all offsets are in **words** (4 bytes) for the TAM (stack of word-sized memory cells).

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Fact: the number of registers is **strictly limited** (from a few to a few dozen)

- The naive code-generation scheme could **fail** because it risks running out of registers.

Better Code (1)

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Note: even the naive code-generation scheme employed a simple register allocation strategy for keeping intermediate results in registers as opposed to storing them in memory.

Better Code (2)

R0 used for x , R1 for y , R2 for z , R5 for n .

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load  R0, [LB - 8]      ; offset(x) = -8
mul   R3, R0, R0        ;  $R3 := x^2$ 
load  R1, [LB - 4]     ; offset(y) = -4
mul   R4, R1, R1        ;  $R4 := y^2$ 
add   R2, R3, R4        ;  $R2 := x^2 + y^2$ 
load  R5, [SB + 168]   ; offset(n) = 4 × 42
mul   R6, R5, R2        ;  $R6 := n(x^2 + y^2)$ 
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load  R5, [SB + 168]   ; offset(n) = 4 × 42
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mul   R6, R5, R2       ;  $R6 := n(x^2 + y^2)$ 
```

- Fewer loads and stores
- Shorter code
- Fewer registers used

Saving Registers Across Calls (1)

Assume the calling convention is that the first three arguments are passed in registers R0, R1, R2 and the result is returned in R0.

Consider the following code fragment:

```
add    R5, R6, R7        ; R5 :=  $x + y$ 
load   R0, [SB + 168]    ; R0 :=  $n$ 
call   factorial         ; R0 :=  $n!$ 
mul    R0, R5, R0        ; R0 :=  $(x + y) \times n!$ 
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```

But what if `factorial` uses some registers, in particular `R5` as manifestly in use across the call?

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In practice, often a mixed approach: some registers are designated caller-saves, others callee-saves.

Interprocedural optimization could improve code further.

Saving Registers Across Calls (3)

Assuming R5 is a caller-saves register and the only register that is in use across the call, the code fragment becomes:

```
add    R5, R6, R7      ; R5 := x + y
load   R0, [SB + 168]  ; R0 := n
store  R5, [LB + 30]   ; Save R5
call   factorial       ; R0 := n!
load   R5, [LB + 30]   ; Restore R5
mul    R0, R5, R0      ; R0 := (x + y) × n!
```

(LB + 30 is assumed to be address of free space in the temporary area.)

Automatic Register Allocation

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Automatic Register Allocation

How can we:

- **Automatically** decide which registers to use?
- Keep the number of registers used **down**?
 - Only a fixed, small number of registers available.
 - Each register must thus be used for many purposes.

Register Pressure

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Desirable to keep register pressure low:

- Minimizing the pressure maximizes the size of the code for which no auxiliary storage (primary memory) is needed.
- Low pressure means fewer registers to preserve (in primary memory) across subroutine calls (both caller and callee saves schemes).

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- Need to take ***liveness*** of variables and intermediate results into account to make it possible to use ***one*** register for ***many*** purposes.
- A variable v is ***live*** at point p if there is an execution path from p to a use of v along which v is not updated.
- No need to keep dead variables in registers!

Liveness (2)

Example:

```
1  x := 3 * m;  
2  y := 42 + x;  
3  z := y * x;  
4  if z > 0 then u := x else u := 0;  
5  y := u;  
6  return y;
```

- x is **live** immediately before line 4 because it **may** be used at line 4.
- y from line 2 is **dead** immediately before line 4 because y is **updated** before being used again.

Liveness (3)

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- u is **dead** before line 4 because it is updated in **both** branches of the `if` at line 4.

Liveness (4)

But consider this variation instead:

```
1  x := 3 * m;  
2  y := 42 + x;  
3  z := y * x;  
4  if z > 0 then u := x else v := 0;  
5  y := u;  
6  return y;
```

- Now u is **live** before line 4 because there exists at least one path to the use of u at line 5 along which u is not updated.

Exercise: Liveness

Consider:

```
1  i := m;  
2  n := 1;  
3  while (i < 10) do begin  
4      n := n * p;  
5      i := i + 1  
6  end  
7  return n;
```

Which of i , m , n , p are live immediately before:

- line 1
- line 3
- line 5
- line 7

Liveness for the Running Example

```
load  R0, [LB - 8]      ;  $offset(x) = -8$ 
mul   R3, R0, R0        ;  $R3 := x^2$ 
load  R1, [LB - 4]      ;  $offset(y) = -4$ 
mul   R4, R1, R1        ;  $R4 := y^2$ 
add   R2, R3, R4        ;  $R2 := x^2 + y^2$ 
load  R5, [SB + 168]    ;  $offset(n) = 4 \times 42$ 
mul   R6, R5, R2        ;  $R6 := n(x^2 + y^2)$ 
```

- x (R0) and y (R1) only used once.
- z (R2) is alive only for a short time, and only once x and y are dead.
- n (R5), interm. results (R4, R6) also short-lived.

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- Each colour corresponds to a register.

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- Add an edge between two nodes if the variables are live simultaneously.
- Colour the graph so that no two **adjacent** nodes get the same colour, using as **few colours** as possible.
- Each colour corresponds to a register.
- Hard optimization problem (NP-complete).

Example: Interference Graph

Consider:

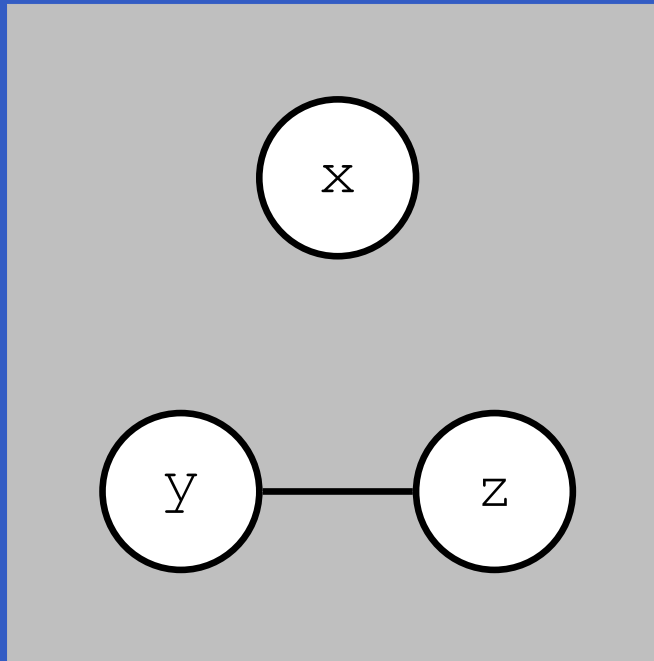
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return y * z
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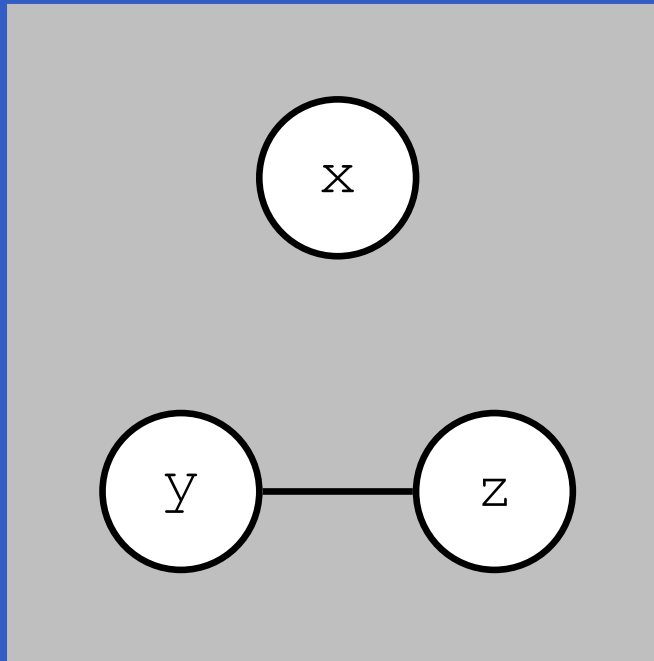


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```

- Draw and colour the interference graph
- Use the result to do a register allocation with the minimal number of registers.

Code Using Minimal Number of Regs

The number of registers used reduced from 7 to 2:

```
load  R0, [LB - 8]      ; offset(x) = -8
mul   R0, R0, R0        ;  $R0 := x^2$ 
load  R1, [LB - 4]      ; offset(y) = -4
mul   R1, R1, R1        ;  $R1 := y^2$ 
add   R0, R0, R1        ;  $R0 := x^2 + y^2$ 
load  R1, [SB + 168]    ; offset(n) = 4 × 42
mul   R0, R1, R0        ;  $R0 := n(x^2 + y^2)$ 
```

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Note: above we started from a code where basic (ad hoc) register allocation already had been done for illustrative purposes.

Register Spilling

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 - **Register Spilling**: storing the content of a register into memory so as to free it and thus reduce the register pressure.
 - Intermediate results stored into the the “temporary” storage area of the stack frame/activation record.
 - Deciding **which** register(s) to spill is (another) hard optimization problem.

Register Spilling: Example (1)

Consider:

$$x * x + y * z$$

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$$x * x + y * z$$

If three or more registers available:

```
load  R0, [LB - 8]      ; offset(x) = -8
mul   R0, R0, R0        ; R0 := x2
load  R1, [LB - 4]      ; offset(y) = -4
load  R2, [LB + 12]     ; offset(z) = 12
mul   R1, R1, R2        ; R1 := yz
add   R0, R0, R1        ; R0 := x2 + yz
```

Register Spilling: Example (2)

$$x * x + y * z$$

If only two registers available ?

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If only two registers available :

```
load  R0, [LB - 8]      ; offset(x) = -8
mul   R0, R0, R0        ;  $R0 := x^2$ 
load  R1, [LB - 4]     ; offset(y) = -4
store R0, [LB + 16]    ; Temporary storage
load  R0, [LB + 12]    ; offset(z) = 12
mul   R0, R1, R0       ;  $R0 := yz$ 
load  R1, [LB + 16]    ;  $R1 := x^2$ 
add   R0, R1, R0       ;  $R0 := x^2 + yz$ 
```

Is Fewer Registers Always Better? (1)

We have seen there are reasons to minimize the number of registers used:

- Ability to get by with as few registers as possible reduces likelihood of having to spill.
- Fewer registers to save and restore across subroutine calls.

Is Fewer Registers Always Better? (2)

But can there be downsides to not making use of all registers there are?

Consider:

```
add    R2, R0, R1
store  R2, [...]
mul    R3, R0, R1
```

A **superscalar** CPU can execute the `add` and `mul` instructions in **parallel** because there is no data dependence between them.

Is Fewer Registers Always Better? (3)

Consider instead:

```
add    R2, R0, R1
store  R2, [...]
mul    R2, R0, R1
```

One fewer registers used, but no longer possible to execute `add` and `mul` in parallel!

`mul` is **anti-dependent** on `store` (or Write After Read (WAR) dependent).

Reducing the number of used registers might have **hurt** the performance!

Is Fewer Registers Always Better? (4)

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But then again, a really clever CPU might use hardware **register renaming**: using extra registers behind the scenes.

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Commonly used; e.g. Pentium II/III/4, Athlon.

See e.g. Wikipedia for details.

Register Allocation: Complications

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- Special purpose registers; e.g. dedicated registers for result of multiplication, memory addressing, etc.
- Registers of varying size.
- Non-uniform instruction set, and thus complicated interaction between code selection and register allocation.