# Model checking coalitional games in shortage resource scenarios

#### Dario Della Monica

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Joint work with Margherita Napoli and Mimmo Parente

LRBA @ ESSLLI 2015

Barcelona, August 2015

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#### Context

- Multi-Agent Systems (MAS)
- MAS + resource constraints

ATL RB-ATL / RAL

- Our proposal: *Priced* RB-ATL
  - Model checking (lower bound)
  - Optimization problem



#### PRB-ATL

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#### 3 Conclusions and future work

ATL RB-ATL / RAL

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#### Several agents

Intelligent (take decisions, moves)

- Independent
- Global state (union of single states)
- Next state univocally identified by moves

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#### **COALITION** - modeling collective behaviors/strategies

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#### **COALITION** - modeling collective behaviors/strategies

Logical Formalisms

Coalition Logic (CL) and Alternating-time Temporal Logic (ATL)

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#### **COALITION** - modeling collective behaviors/strategies

Logical Formalisms

Coalition Logic (CL) and Alternating-time Temporal Logic (ATL)

Theorem (Goranko, TARK 2001)

CL can be embedded into ATL

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Formulae of ATL are given by the grammar:

$$\varphi ::= p \mid \neg \varphi \mid \varphi \land \varphi \mid \langle \langle \mathbf{A} \rangle \rangle \bigcirc \varphi \mid \langle \langle \mathbf{A} \rangle \rangle \Box \varphi \mid \langle \langle \mathbf{A} \rangle \rangle \varphi \mathcal{U} \varphi$$

Formulae of ATL predicate about abilities of coalitions of agents

Model checking coalitional games in shortage resource scenarios (LRBA @ ESSLLI 2015)

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Formulae of ATL predicate about abilities of coalitions of agents

Formulae of ATL are evaluated wrt:

- a game structure (or game arena) G
- a location q of G

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A game structure G is a state transition graph:



vertices labeled by atomic propositions

- in vertices agents choose actions

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Model checking coalitional games in shortage resource scenarios (LRBA @ ESSLLI 2015)

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 $\langle \langle A \rangle \rangle \bigcirc p$  next  $\langle \langle A \rangle \rangle \Box p$  always  $\langle \langle A \rangle \rangle p \mathcal{U} q$  until q

Model checking coalitional games in shortage resource scenarios (LRBA @ ESSLLI 2015)

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 $\langle \langle A \rangle \rangle \bigcirc p$  next  $\langle \langle A \rangle \rangle \Box p$  always

 $\langle \langle A \rangle \rangle p \mathcal{U} q$  until q

regardless of actions performed by other agents (opponent)

Model checking coalitional games in shortage resource scenarios (LRBA @ ESSLLI 2015)

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Model checking coalitional games in shortage resource scenarios (LRBA @ ESSLLI 2015)

## Addition of bounds on resources to ATL



#### Extensions of ATL with bounds on resources

 $\langle \langle A^{\eta} \rangle \rangle \Box p$ Endowment:  $\eta : A \to \mathbb{N}^r$  (r = number of resources)

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#### RB-ATL [Alechina, Logan, Nga, Rakib, AAMAS 2010]

Model checking RB-ATL is decidable in  $O(|\varphi|^{2 \cdot r+1} \times |G|)$ No lower bound

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Several logic variants, exploration of the (un)decidability border E.g., if actions produce resources, Model Checking is generally UNDECIDABLE

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#### Decidability [Alechina, Logan, Nga, Raimondi, ECAI 2014]

Under some conditions, RB $\pm$ ATL (with production) is decidable No upper bound

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#### Unification [Alechina, Bulling, Logan, Nga, IJCAI 2015]

Unifying several approaches and exploring decidability borders

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Formulae of RB-ATL are given by the grammar:

 $\varphi ::= p \mid \neg \varphi \mid \varphi \land \varphi \mid \langle \langle \mathbf{A}^{\eta} \rangle \rangle \bigcirc \varphi \mid \langle \langle \mathbf{A}^{\eta} \rangle \rangle \varphi \mathcal{U} \varphi \mid \langle \langle \mathbf{A}^{\eta} \rangle \rangle \Box \varphi$ 

Formulae of RB-ATL predicate about abilities of coalitions whose agents are equipped with an endowment of resources

Formulae of RB-ATL are evaluated wrt:

- a resource-bounded game structure (or game arena) G
- a location q of G

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A resource-bounded game structure G is a weighted state transition graph:



- vertices labeled by atomic propositions
- in vertices agents choose actions
- possible combinations → transitions (edges of the graph)
- actions consume (and produce) resources

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# Becoming friendly with RB-ATL



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# Becoming friendly with RB-ATL

# $\langle\langle {\cal A}^\eta \rangle\rangle \bigcirc \langle\langle {\cal A}^{\eta'} \rangle\rangle \Box {\cal P}$

team *A*, equipped with endowment  $\eta$ , can force the next state to be s.t. team *A* itself, equipped with the new endowment  $\eta'$ , can guarantee that *p* always holds

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## Shared resources: Example

2 agents: **a** and **b** 1 resource type: **r**<sub>1</sub>  $G, q_0 \Vdash \langle \langle a^\eta \rangle \rangle \Diamond p$ 



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false with private endowment  $\eta(a) = any$  $\eta(b) > 0$ 

true with shared resources

Model checking coalitional games in shortage resource scenarios (LRBA @ ESSLLI 2015)

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true with shared resources

#### proponent has the ability of consuming all resources to make opponent weak

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# Outline

## Context

Multi-Agent Systems (MAS)

MAS + resource constraints



Model checking (lower bound)Optimization problem



ATL RB-ATL / RAL

## PRB-ATL

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Public/shared resources + private ones (money)

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Public/shared resources + private ones (money)

- $\Rightarrow$  global availability of resources on the market
  - a semantic component (part of the arena)
  - evolves depending on agents' actions (also opponent)
  - affects the choice of the actions (also opponent)

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Public/shared resources + private ones (money)

- $\Rightarrow$  global availability of resources on the market
  - a semantic component (part of the arena)
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## $\Rightarrow$ price of resources

- agents equipped with money (private resources)
- money for getting resources
- price of resources function of several components (take into account the history of the system)

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#### Resources

#### part of the model

- represent the market (nature)
- public: agents draw on resources from a shared pool

#### known

• availability checked for all agents

## Money

#### inside the formula

- assigned to agents
- private: any agent has his own amount of money
- unknown
- availability checked for proponent's agents only

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- unknown
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#### Money is a *meta-resource*

- buy resources
- unit of measurement

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# Resource production and decidability

Alechina, Logan, Nga, Rakib, AAMAS 2010

Actions can **only consume** resources

## Bulling, Farwer, ECAI 2010

If actions produce resources, Model Checking is generally UNDECIDABLE

Alechina, Logan, Nga, Raimondi, ECAI 2014

Under some conditions, RB $\pm$ ATL (with production) is decidable

Model checking coalitional games in shortage resource scenarios (LRBA @ ESSLLI 2015)

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Under some conditions, RB $\pm$ ATL (with production) is decidable

Actions may produce resources... but not so much!!!

- model checking decidable
- several models fit

(e.g. memory usage, leasing a car, releasing resources previously acquired)

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Formulae of PRB-ATL are given by the grammar:

$$\varphi ::= p \mid \neg \varphi \mid \varphi \land \varphi \mid \langle \langle \boldsymbol{A}^{\$} \rangle \rangle \bigcirc \varphi \mid \langle \langle \boldsymbol{A}^{\$} \rangle \rangle \varphi \mathcal{U} \varphi \mid \langle \langle \boldsymbol{A}^{\$} \rangle \rangle \Box \varphi$$

Formulae of PRB-ATL predicate about abilities of coalitions whose agents are equipped with an amount of money

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Formulae of PRB-ATL predicate about abilities of coalitions whose agents are equipped with an amount of money

Formulae of PRB-ATL are evaluated wrt:

- a priced game structure (or game arena) G
- a location q of G
- a global availability of resources  $\vec{m}$

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# Priced game structure

A priced game structure G is a weighted state transition graph:



- vertices labeled by atomic propositions
- in vertices agents choose actions
- possible combinations → **transitions** (edges of the graph)
- actions consume and produce resources
- resources have a variable prices
- transition guards: also opponent

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# Outline

## Context

Multi-Agent Systems (MAS)

MAS + resource constraints

ATL RB-ATL / RAL





## PRB-ATL

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Model checking coalitional games in shortage resource scenarios (LRBA @ ESSLLI 2015)

D. Della Monica

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#### Theorem

The model checking problem for PRB-ATL is EXPTIME-complete

- membership (upper bound)
- hardness (lower bound)

[LAMAS 2011] [GandALF 2013]

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Reduction from the acceptance problem for Linearly-Bounded Alternating Turing Machine

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The algorithm runs in time  $O(|\varphi| \cdot |G| \cdot M^{r+n})$ 

Model checking is exponential in

- *n*: number of agents
- r: number of resources
- size of *M*: max. component in resource/money vectors (when represented in binary)

1st reduction: parametric in the size of M (n and r are constant) 2nd reduction: parametric in r (n and M are constant)

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## 3rd reduction: parametric in *n* (*r* and *M* are constant) OPEN PROBLEM

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#### LB-ATM are Turing Machines

- linearly-bounded: tape length is bounded by a linear function of the size of the input word *w*
- alternating: existential and universal states

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## LB-ATM are Turing Machines

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#### Acceptance condition:

- a computation from an existential state is accepting if at least one computation from that state is accepting
- a computation from a universal state is accepting if every computation from that state is accepting

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## Configurations: (internal state, alphabet symbol in head cell)

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Finite control: 
$$\langle \boldsymbol{q}, \lambda \rangle \rightarrow \langle \boldsymbol{r}_1, \nu_1, \sim_1 \rangle$$
  
 $\langle \boldsymbol{q}, \lambda \rangle \rightarrow \langle \boldsymbol{r}_2, \nu_2, \sim_2 \rangle$   
 $\dots$   
 $\langle \boldsymbol{s}, \gamma \rangle \rightarrow \dots$ 

. . .

 $q, s, r_i \in Q$ : internal states  $\lambda, \gamma, \nu_i \in \Sigma$ : alphabet symbols  $\sim_i \in \{\leftarrow, \rightarrow\}$ : head movements

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# Sketch of the 1st reduction (I)

Encoding of instructions  $\langle q, \lambda \rangle \rightarrow \langle r_i, \nu_i, \sim_i \rangle$  matching a full state  $\langle q, \lambda \rangle$ *q* existential state *q* universal state



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# Encoding of the tape



Model checking coalitional games in shortage resource scenarios (LRBA @ ESSLLI 2015)

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# Sketch of the 1st reduction (II)

Module *shift\_right\_with\_inc* 





Module *plus\_1*( $\mu_L$ )



Module *choose\_next\_state(i, \mu\_L, \mu\_R)* 



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#### Theorem

For each PRB-ATL formula  $\varphi$ , and each priced game structure *G*:

 $[\varphi] = [\varphi]^{ml}.$ 

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# Outline

## Context

Multi-Agent Systems (MAS)

- MAS + resource constraints
- Our proposal: *Priced* RB-ATL
   Model checking (lower bound)
   Optimization problem



ATL RB-ATL / RAL

## PRB-ATL

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• PRB-ATL: 
$$\varphi = \langle \langle A_1^{\$_1} \rangle \rangle \Diamond (\langle \langle A_2^{\$_2} \rangle \bigcirc p \lor \langle \langle A_3^{\$_3} \rangle \rangle q \mathcal{U} p)$$

Definition (Cost of a PRB-ATL formula)

$$f\_cost(\varphi) = \$_1(A_1) + \$_2(A_2) + \$_3(A_3)$$

• parametric PRB-ATL:  $\varphi_{\vec{X}} = \langle \langle X_1^{\$_1} \rangle \rangle \Diamond (\langle \langle X_2^{\$_2} \rangle \bigcirc p \lor \langle \langle A_3^{\$_3} \rangle \rangle q \mathcal{U} p)$ 

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# The Optimal Coalition problem

## Definition (Optimal Coalition problem)

To determine minimal-cost coalitions that satisfy a PRB-ATL formula

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# The Optimal Coalition problem

## Definition (Optimal Coalition problem)

To determine minimal-cost coalitions that satisfy a PRB-ATL formula

Input:

- a parametric PRB-ATL formula
- a priced game structure
- a location
- an initial availability of resources

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#### Theorem

The Optimal Coalition problem is EXPTIME-complete

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# Outline

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# 3 Conclusions and future work

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PRB-ATL

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# Conclusions and future works

## Conclusions

• Theorem: Model checking PRB-ATL is EXPTIME-complete Reachability for PRB-ATL is EXPTIME-complete

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# Conclusions and future works

## Conclusions

• Theorem: Model checking PRB-ATL is EXPTIME-complete Reachability for PRB-ATL is EXPTIME-complete

### **Future works**

- 3rd reduction: parametric in *n* (*r* and *M* are constant)
- Exact complexity when actions cannot produce resources
  - Reachability is NP-hard
  - Model checking is PSPACE-hard
- Expressiveness comparative analysis wrt. other existing formalisms
- Resource-bounded extensions of other classical formalisms
  - µ-calculus
     ATL\*

▶ ...

[Della Monica, Lenzi - ICAART 2012 ???

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# Conclusions and future works

## Conclusions

• Theorem: Model checking PRB-ATL is EXPTIME-complete Reachability for PRB-ATL is EXPTIME-complete

#### **Future works**

▶ ...

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# Thank you!

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