### COMP4075: Lecture 10

Concurrency

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### A Concurrency Monad (2)

Introduce a monad representing "interleavable computations". At this stage, this amounts to little more than a convenient way to construct threads by sequential composition.

How can *Threads* be constructed sequentially? The only way is to parameterize thread prefixes on the rest of the *Thread*. This leads directly to *continuations*.

# **Running a Concurrent Computation (1)**

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```
type Output = [Char]

type ThreadQueue = [Thread]

type State = (Output, ThreadQueue)

runCM :: CM \ a \rightarrow Output

runCM \ m = runHlp \ ("",[]) \ (thread \ m)

where

runHlp \ s \ t =

case dispatch \ s \ t \ of

Left \ (s',t) \rightarrow runHlp \ s' \ t

Right \ o \rightarrow o
```

### **This Lecture**

- A concurrency monad (adapted from Claessen (1999))
- · Basic concurrent programming in Haskell
- Software Transactional Memory (the STM monad)

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# A Concurrency Monad (3)

```
newtype CM a = CM ((a \rightarrow Thread) \rightarrow Thread)

from CM :: CM a \rightarrow ((a \rightarrow Thread) \rightarrow Thread)

from CM (CM \ x) = x

thread :: CM a \rightarrow Thread

thread \ m = from CM \ m \ (const \ End)

instance Monad \ CM where

return \ x = CM \ (\lambda k \rightarrow k \ x)

m \gg f = CM \ \lambda k \rightarrow

from CM \ m \ (\lambda x \rightarrow from CM \ (f \ x) \ k)
```

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# **Running a Concurrent Computation (2)**

Dispatch on the operation of the currently running *Thread*. Then call the scheduler.

```
\begin{array}{l} \textit{dispatch} :: \textit{State} \rightarrow \textit{Thread} \\ \rightarrow \textit{Either} \; (\textit{State}, \textit{Thread}) \; \textit{Output} \\ \textit{dispatch} \; (o, rq) \; (\textit{Print} \; c \; t) = \\ \textit{schedule} \; (o + [\; c\;], rq + [\; t\;]) \\ \textit{dispatch} \; (o, rq) \; (\textit{Fork} \; t1 \; t2) = \\ \textit{schedule} \; (o, rq + [\; t1, t2\;]) \\ \textit{dispatch} \; (o, rq) \; \textit{End} = \\ \textit{schedule} \; (o, rq) \end{array}
```

# A Concurrency Monad (1)

A *Thread* represents a (branching) process: a stream of primitive *atomic* operations:

```
 \begin{aligned} \textbf{data} \ \textit{Thread} &= \textit{Print Char Thread} \\ &\mid \textit{Fork Thread Thread} \\ &\mid \textit{End} \end{aligned}
```

Note that a  $\mathit{Thread}$  represents the  $\mathit{entire rest}$  of a computation.

Note also that a *Thread* can spawn other *Threads* (so we get a tree, if you prefer).

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# A Concurrency Monad (4)

### Atomic operations:

```
\begin{array}{l} cPrint::Char\to CM\ ()\\ cPrint\ c=CM\ (\lambda k\to Print\ c\ (k\ ()))\\ cFork::CM\ a\to CM\ ()\\ cFork\ m=CM\ (\lambda k\to Fork\ (thread\ m)\ (k\ ()))\\ cEnd::CM\ a\\ cEnd=CM\ (\diagdown\to End) \end{array}
```

# **Running a Concurrent Computation (3)**

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Selects next *Thread* to run, if any.

```
schedule :: State \rightarrow Either (State, Thread)
Output
schedule (o,[]) = Right o
schedule (o, t : ts) = Left ((o, ts), t)
```

This all amounts to a *topological sorting* of the nodes in the *Thread*-tree.

### **Example: Concurrent Processes**

```
p1 :: CM ()
                  p2 :: CM ()
                                     p3 :: CM ()
                                    p\beta = \mathbf{do}
p1 = \mathbf{do}
                  p2 = \mathbf{do}
                     cPrint '1'
  cPrint 'a'
                                       cFork p1
  cPrint 'b'
                     cPrint '2'
                                       cPrint 'A'
                                       cFork p2
  cPrint 'i'
                     cPrint '0'
                                       cPrint 'B'
main = print (runCM p3)
```

Result: aAbc1Bd2e3f4g5h6i7j890

Note: As it stands, the output is only made available after all threads have terminated.)

# Any Use?

- Illustrates the flexibility offered by monads for introducing new control abstractions, including on top of basic concurrency primitives (cf. Control. Concurrent. Asynch).
- A number of libraries and embedded langauges use similar ideas, e.g.
  - Fudgets: A GUI library
  - Yampa: A FRP library
- Studying semantics of concurrent programs.
- Aid for testing, debugging, and reasoning about concurrent programs.

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# **Example: Basic Synchronization (1)**

```
\begin{tabular}{ll} {\bf module} \begin{tabular}{ll} {\bf Main} \begin{tabular}{ll} {\bf where} \\ {\bf import} \begin{tabular}{ll} {\bf Concurrent} \\ {\bf count} {\bf From} {\bf To} :: {\bf Int} \rightarrow {\bf Int} \rightarrow {\bf IO} \ () \\ {\bf count} {\bf From} {\bf To} \ m \ n \\ & | \ m > n \  & = return \ () \\ & | \ otherwise = {\bf do} \\ & put StrLn \ (show \ m) \\ & count {\bf From} {\bf To} \ (m+1) \ n \\ \end{tabular}
```

# **Incremental Output**

#### Incremental output:

```
\begin{array}{l} runCM :: CM \ a \rightarrow Output \\ runCM \ m = dispatch \ [] \ (thread \ m) \\ dispatch :: ThreadQueue \rightarrow Thread \rightarrow Output \\ dispatch \ rq \ (Print \ c \ t) = c : schedule \ (rq + [t]) \\ dispatch \ rq \ (Fork \ t1 \ t2) = schedule \ (rq + [t1, t2]) \\ dispatch \ rq \ End = schedule \ rq \\ schedule :: ThreadQueue \rightarrow Output \\ schedule \ [] = [] \\ schedule \ (t : ts) = dispatch \ ts \ t \\ \end{array}
```

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# **Concurrent Programming in Haskell**

Primitives for concurrent programming provided as operations of the IO monad. They are in the module *Control Concurrent*. Excerpts:

```
 \begin{array}{ll} fork IO & :: IO \ () \rightarrow IO \ Thread Id \\ kill Thread & :: Thread Id \rightarrow IO \ () \\ thread Delay & :: Int \rightarrow IO \ () \\ new MVar & :: a \rightarrow IO \ (MVar \ a) \\ new Empty MVar :: IO \ (MVar \ a) \\ put MVar & :: MVar \ a \rightarrow a \rightarrow IO \ () \\ take MVar & :: MVar \ a \rightarrow IO \ a \\ \end{array}
```

# **Example: Basic Synchronization (2)**

```
main = \mathbf{do}
start \leftarrow newEmptyMVar
done \leftarrow newEmptyMVar
forkIO \$ \mathbf{do}
takeMVar \ start
countFromTo \ 1 \ 10
putMVar \ done \ ()
putStrLn \ "Go!"
putMVar \ start \ ()
takeMVar \ done
countFromTo \ 11 \ 20
putStrLn \ "Done!"
```

## **Example: Concurrent processes 2**

```
p1 :: CM ()
                p2 :: CM ()
                                 p3 :: CM ()
p1 = do
                p2 = \mathbf{do}
                                 p\beta = do
                  cPrint '1'
  cPrint 'a'
                                   cFork v1
  cPrint 'b'
                  undefined
                                   cPrint 'A'
                                   cFork p2
  cPrint'i'
                  cPrint '0'
                                   cPrint 'B'
main = print (runCM p3)
```

**Result**: aAbc1Bd \* \* \* Exception : Prelude.undefined

### **MVars**

- The fundamental synchronisation mechanism is the *MVar* ("em-var").
- An MVar is a "one-item box" that may be empty or full.
- Reading (takeMVar) and writing (putMVar) are atomic operations:
  - Writing to an empty MVar makes it full.
  - Writing to a full MVar blocks.
  - Reading from an empty MVar blocks.
  - Reading from a full MVar makes it empty.

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# **Example: Unbounded Buffer (1)**

```
module Main where

import Control.Monad (when)

import Control.Concurrent

newtype Buffer a =

Buffer (MVar (Either [a] (Int, MVar a)))

newBuffer :: IO (Buffer a)

newBuffer = \mathbf{do}

b \leftarrow newMVar (Left [])

return (Buffer b)
```

# **Example: Unbounded Buffer (2)**

```
readBuffer :: Buffer \ a \to IO \ a
readBuffer \ (Buffer \ b) = \mathbf{do}
bc \leftarrow takeMVar \ b
\mathbf{case} \ bc \ \mathbf{of}
Left \ (x:xs) \to \mathbf{do}
putMVar \ b \ (Left \ xs)
return \ x
Left \ [] \to \mathbf{do}
w \leftarrow newEmptyMVar
putMVar \ b \ (Right \ (1, w))
takeMVar \ w
```

# **Example: Unbounded Buffer (4)**

The buffer can now be used as a channel of communication between a set of "writers" and a set of "readers". E.g.:

```
main = \mathbf{do}

b \leftarrow newBuffer

forkIO\ (writer\ b)

forkIO\ (reader\ b)

forkIO\ (reader\ b)
```

# **Compositionality? (2)**

What about this?

```
mutex \leftarrow newMVar ()

...
takeMVar \ mutex
x1 \leftarrow readBuffer \ b
x2 \leftarrow readBuffer \ b
putMVar \ mutex ()
```

# **Example: Unbounded Buffer (3)**

```
Right (n, w) \to \mathbf{do}

putMVar\ b\ (Right\ (n+1, w))

takeMVar\ w
```

# **Example: Unbounded Buffer (5)**

```
reader :: Buffer Int \rightarrow IO ()
reader n b = rLoop

where

rLoop = \mathbf{do}

x \leftarrow readBuffer b

when (x > 0) \$ \mathbf{do}

putStrLn (n + ": " + show x)
rLoop
```

# **Compositionality? (3)**

Suppose we would like to read from *one of two* buffers.

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That is, *composing alternatives*.

Hmmm. How do we even begin?

- No way to attempt reading a buffer without risking blocking.
- We have to change or enrich the buffer implementation. E.g. add a tryReadBuffer operation, and then repeatedly poll the two buffers in a tight loop. Not so good!

## **Example: Unbounded Buffer (4)**

```
\label{eq:writeBuffer} writeBuffer :: Buffer \ a \to a \to IO\ () \label{eq:writeBuffer} writeBuffer \ (Buffer \ b) \ x = \mathbf{do} bc \leftarrow takeMVar \ b \mathbf{case} \ bc \ \mathbf{of} Left \ xs \to putMVar \ b \ (Left \ (xs + [x])) Right \ (n,w) \to \mathbf{do} putMVar \ w \ x \mathbf{if} \ n > 1 \mathbf{then} \ putMVar \ b \ (Right \ (n-1,w)) \mathbf{else} \ putMVar \ b \ (Left \ [])
```

### **Compositionality?** (1)

Suppose we would like to read two *consecutive* elements from a buffer b?

That is, *sequential composition*.

Would the following work?

```
x1 \leftarrow readBuffer \ b
x2 \leftarrow readBuffer \ b
```

# **Software Transactional Memory (1)**

- Operations on shared mutable variables grouped into *transactions*.
- A transaction either succeeds or fails in its entirety. I.e., atomic w.r.t. other transactions.
- Failed transactions are automatically retried until they succeed.
- Transaction logs, which records reading and writing of shared variables, maintained to enable transactions to be validated, partial transactions to be rolled back, and to determine when worth trying a transaction again.

# **Software Transactional Memory (2)**

- Basic consistency requirement: The effects of reading and writing within a transaction must be indistinguishable from the transaction having been carried out in isolation.
- No locks! (At the application level.)

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# **Example: Buffer Revisited (1)**

Unbounded buffer using the STM monad:

```
module Main where import Control.Monad (when) import Control.Concurrent import Control.Concurrent.STM newtype Buffer \ a = Buffer \ (TVar \ [a]) newBuffer :: STM \ (Buffer \ a) newBuffer = \mathbf{do} b \leftarrow newTVar \ [] return \ (Buffer \ b)
```

# **Example: Buffer Revisited (4)**

The main program and code for readers and writers can remain unchanged, except that STM operations must be carried out *atomically*:

```
main = \mathbf{do}

b \leftarrow atomically newBuffer

forkIO (writer b)

forkIO (writer b)

forkIO (reader b)

forkIO (reader b)
```

# **STM and Pure Declarative Languages**

- STM perfect match for purely declarative languages:
  - reading and writing of shared mutable variables explicit and relatively rare;
  - most computations are pure and need not be logged.
- Disciplined use of effects through monads a huge payoff: easy to ensure that only effects that can be undone can go inside a transaction.

(Imagine the havoc of arbitrary I/O actions if part of transaction: How to undo? What if retried?)

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# **Example: Buffer Revisited (2)**

```
readBuffer :: Buffer \ a 	o STM \ a
readBuffer \ (Buffer \ b) = \mathbf{do}
xs \leftarrow readTVar \ b
\mathbf{case} \ xs \ \mathbf{of}
[] \rightarrow retry
(x : xs') \rightarrow \mathbf{do}
writeTVar \ b \ xs'
return \ x
```

# **Example: Buffer Revisited (5)**

```
reader :: Buffer Int \rightarrow IO ()
reader n b = rLoop

where

rLoop = do

x \leftarrow atomically (readBuffer b)

when (x > 0) $ do

putStrLn (n + ": " + show x)

rLoop
```

### The STM monad

The software transactional memory abstraction provided by a monad STM. **Distinct from IO!** Defined in Control.Concurrent.STM.

#### Excerpts:

```
\begin{array}{ll} newTVar & :: a \rightarrow STM \ (TVar \ a) \\ writeTVar :: TVar \ a \rightarrow a \rightarrow STM \ () \\ readTVar & :: TVar \ a \rightarrow STM \ a \\ retry & :: STM \ a \\ atomically :: STM \ a \rightarrow IO \ a \end{array}
```

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## **Example: Buffer Revisited (3)**

```
writeBuffer :: Buffer \ a \to a \to STM \ ()

writeBuffer \ (Buffer \ b) \ x = \mathbf{do}

xs \leftarrow readTVar \ b

writeTVar \ b \ (xs ++ [x])
```

# **Composition (1)**

STM operations can be **robustly composed**. That's the reason for making readBuffer and  $writeBuffer\ STM$  operations, and leaving it to client code to decide the scope of atomic blocks.

Example, sequential composition: reading two consecutive elements from a buffer *b*:

```
atomically \$ do
x1 \leftarrow readBuffer b
x2 \leftarrow readBuffer b
```

# **Composition (2)**

Example, composing alternatives: reading from one of two buffers b1 and b2:

```
x \leftarrow atomically \$
readBuffer \ b1
`orElse` readBuffer \ b2
```

The buffer operations thus composes nicely. No need to change the implementation of any of the operations!

# **Further STM Functionality (3)**

Other process communication and synchronization facilities:

- TChan a: Unbounded FIFO channel
- TQueue a: Variation of TChan with faster (amortised) throughput.
- TBQueue a: Bounded FIFO channel
- TSem: Transactional counting semaphore

# **Further STM Functionality (1)**

TMVar: STM version of MVars for synchoronisation; built on top of TVars:

 $TMVar\ a \approx TVar\ (Maybe\ a)$ 

#### Some operations:

- $newTMVar :: a \rightarrow STM \ (TMVar \ a)$
- newEmptyTMVar :: STM (TMVar a)
- $putTMVar :: TMVar \ a \rightarrow a \rightarrow STM$  ()
- $takeTMVar :: TMVar \ a \rightarrow STM \ a$
- $readTMVar :: TMVar \ a \rightarrow STM \ a$
- $swapTMVar :: TMVar \ a \rightarrow a \rightarrow STM \ a$

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# Reading

- Koen Claessen. A Poor Man's Concurrency Monad.
   Journal of Functional Programming, 9(3), 1999.
- Wouter Swierstra and Thorsten Altenkirch. Beauty in the Beast: A Functional Semantics for the Awkward Squad. In Proceedings of Haskell'07, 2007.
- Tim Harris, Simon Marlow, Simon Peyton Jones, Maurice Herlihy. Composable Memory Transactions. In Proceedings of PPoPP'05, 2005
- Simon Peyton Jones. Beautiful Concurrency. Chapter from Beautiful Code, ed. Greg Wilson, O'Reilly 2007.

# **Further STM Functionality (2)**

#### Some non-blocking operations:

- $isEmptyTMVar :: TMVar \ a \rightarrow STM \ Bool$
- $tryPutTMVar :: TMVar \ a \rightarrow a \rightarrow STM \ Bool$
- $tryTakeTMVar :: TMVar \ a \rightarrow STM \ (Maybe \ a)$
- $tryReadTMVar :: TMVar \ a \rightarrow STM \ (Maybe \ a)$