

MGS 2007: ADV Lecture 3

Arrows and Functional Reactive Programming

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Arrows (3)

John Hughes' **arrow** framework:

- Abstract data type interface for function-like types (or "blocks", if you prefer).
- Particularly suitable for types representing process-like computations.
- Related to **monads**, since arrows are computations, but more general.
- Provides a minimal set of "wiring" combinators.

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The Arrow class

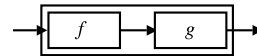
In Haskell, a **type class** is used to capture these ideas (except for the laws):

```
class Arrow a where
  arr    :: (b -> c) -> a b c
  (>>>) :: a b c -> a c d -> a b d
  first :: a b c -> a (b,d) (c,d)
```

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Arrows (1)

System descriptions in the form of block diagrams are very common. Blocks have inputs and outputs and can be combined into larger blocks. For example, serial composition:



A *combinator* can be defined that captures this idea:

```
(>>>) :: B a b -> B b c -> B a c
```

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What is an arrow? (1)

- A **type constructor** a of arity two.
- Three operators:
 - **lifting**:
 $\text{arr} :: (b \rightarrow c) \rightarrow a b c$
 - **composition**:
 $(>>>) :: a b c \rightarrow a c d \rightarrow a b d$
 - **widening**:
 $\text{first} :: a b c \rightarrow a (b,d) (c,d)$
- A set of **algebraic laws** that must hold.

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Functions are arrows (1)

Functions are a simple example of arrows, with (\rightarrow) as the arrow type constructor.

Exercise 1: Suggest suitable definitions of

- arr
- $(>>>)$
- first

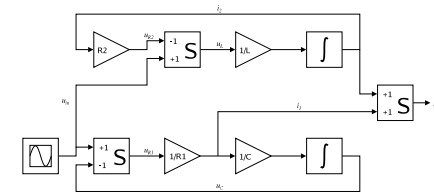
for this case!

(We have not looked at what the laws are yet, but they are "natural".)

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Arrows (2)

But systems can be complex:

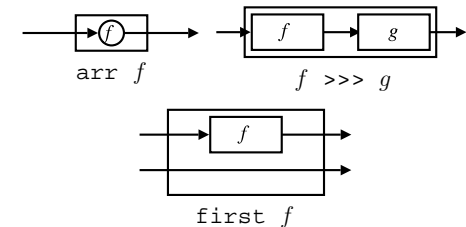


How many and what combinators do we need to be able to describe arbitrary systems?

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What is an arrow? (2)

These diagrams convey the general idea:



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Functions are arrows (2)

Solution:

- $\text{arr} = \text{id}$
To see this, recall
 $\text{id} :: t \rightarrow t$
 $\text{arr} :: (b \rightarrow c) \rightarrow a b c$

Instantiate with

```
a = (->)
t = b->c = (->) b c
```

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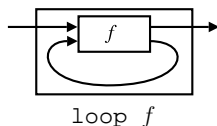
Functions are arrows (3)

- `f >>> g = \a -> g (f a)` **or**
- `f >>> g = g . f` **or even**
- `(>>>) = flip (.)`
- `first f = \ (b,d) -> (f b,d)`

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The loop combinator (1)

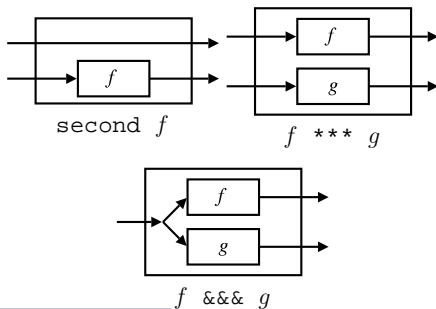
Another important operator is `loop`: a fixed-point operator used to express recursive arrows or **feedback**:



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Some more arrow combinators (2)

As diagrams:



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Functions are arrows (4)

Arrow instance declaration for functions:

```
instance Arrow (->) where
  arr      = id
  (>>>)   = flip (.)
  first f = \ (b,d) -> (f b,d)
```

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The loop combinator (2)

Not all arrow instances support `loop`. It is thus a method of a separate class:

```
class Arrow a => ArrowLoop a where
  loop :: a (b, d) (c, d) -> a b c
```

Remarkably, the four combinators `arr`, `>>>`, `first`, and `loop` are sufficient to express any conceivable wiring!

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Some more arrow combinators (3)

```
second :: Arrow a => a b c -> a (d,b) (d,c)
second f = arr swap >>> first f >>> arr swap
swap (x,y) = (y,x)
```

```
(***) :: Arrow a =>
  a b c -> a d e -> a (b,d) (c,e)
f *** g = first f >>> second g
```

```
(&&&) :: Arrow a => a b c -> a b d -> a b (c,d)
f &&& g = arr (\x->(x,x)) >>> (f *** g)
```

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Some arrow laws

```
(f >>> g) >>> h = f >>> (g >>> h)
arr (f >>> g) = arr f >>> arr g
arr id >>> f = f
f = f >>> arr id
first (arr f) = arr (first f)
first (f >>> g) = first f >>> first g
```

Exercise 2: Draw diagrams illustrating the first and last law!

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Some more arrow combinators (1)

```
second :: Arrow a =>
  a b c -> a (d,b) (d,c)
```

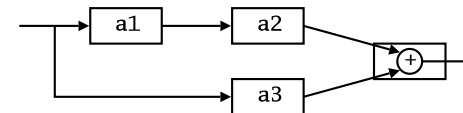
```
(***) :: Arrow a =>
  a b c -> a d e -> a (b,d) (c,e)
```

```
(&&&) :: Arrow a =>
  a b c -> a b d -> a b (c,d)
```

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Exercise 3

Describe the following circuit using arrow combinators:

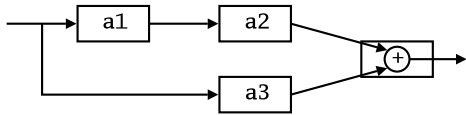


`a1`, `a2`, `a3` :: A Double Double

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Exercise 3: One solution

Exercise 3: Describe the following circuit using arrow combinators:



`a1, a2, a3 :: A Double Double`

```

circuit_v1 :: A Double Double
circuit_v1 = (a1 &&& arr id)
            >>> (a2 *** a3)
            >>> arr (uncurry (+))
    
```

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Note on the definition of (***) (2)

Similarly

$(f *** g) >>> (h *** k) \neq (f >>> h) *** (g >>> k)$

since the order of *f* and *g* differs.

However, the following **is** true (an additional law):

```

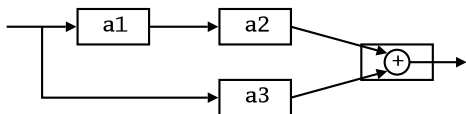
first f >>> second (arr g)
= second (arr g) >>> first f
    
```

However, for certain **arrow instances** equalities like the ones above do hold.

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The arrow do notation (2)

Let us redo exercise 3 using this notation:



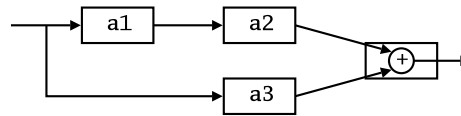
```

circuit_v4 :: A Double Double
circuit_v4 = proc x -> do
  y1 <- a1 -< x
  y2 <- a2 -< y1
  y3 <- a3 -< x
  returnA -< y2 + y3
    
```

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Exercise 3: Another solution

Exercise 3: Describe the following circuit:



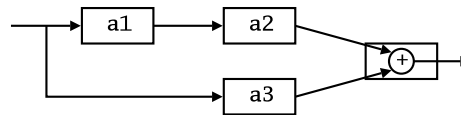
`a1, a2, a3 :: A Double Double`

```

circuit_v2 :: A Double Double
circuit_v2 = arr (\x -> (x,x))
            >>> first a1
            >>> (a2 *** a3)
            >>> arr (uncurry (+))
    
```

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Yet an attempt at exercise 3



```

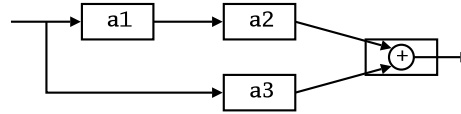
circuit_v3 :: A Double Double
circuit_v3 = (a1 &&& a3)
            >>> first a2
            >>> arr (uncurry (+))
    
```

Exercise 4: Are `circuit_v1`, `circuit_v2`, and `circuit_v3` all equivalent?

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The arrow do notation (3)

We can also mix and match:



```

circuit_v5 :: A Double Double
circuit_v5 = proc x -> do
  y2 <- a2 <<< a1 -< x
  y3 <- a3 -< x
  returnA -< y2 + y3
    
```

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Note on the definition of (***) (1)

Are the following two definitions of (***) equivalent?

- $f *** g = \text{first } f \gg \gg \text{second } g$
- $f *** g = \text{second } g \gg \gg \text{first } f$

No, in general

$\text{first } f \gg \gg \text{second } g \neq \text{second } g \gg \gg \text{first } f$

since the **order** of the two possibly effectful computations *f* and *g* are different.

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The arrow do notation (1)

Ross Paterson's `do`-notation for arrows supports **pointed** arrow programming. Only **syntactic sugar**.

```

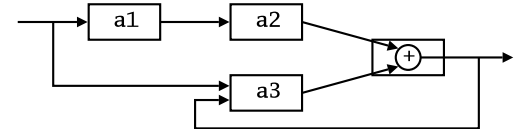
proc pat -> do [ rec ]
  pat1 <- sfxp1 -< exp1
  pat2 <- sfxp2 -< exp2
  ...
  patn <- sfxpn -< expn
  returnA -< exp
    
```

Also: `let pat = exp` \equiv `pat <- arr id -< exp`

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The arrow do notation (4)

Recursive networks: `do`-notation:

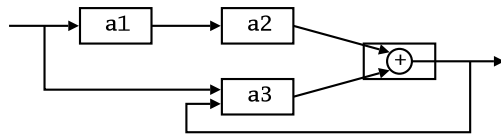


`a1, a2 :: A Double Double`
`a3 :: A (Double,Double) Double`

Exercise 5: Describe this using only the arrow combinators.

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The arrow do notation (5)



```

circuit = proc x -> do
  rec
    y1 <- a1 -< x
    y2 <- a2 -< y1
    y3 <- a3 -< (x, y)
    let y = y2 + y3
  returnA -< y
  
```

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Arrows and Monads (1)

Arrows generalize monads: for every monad type there is an arrow, the **Kleisli category** for the monad:

```

newtype Kleisli m a b = K (a -> m b)

instance Monad m => Arrow (Kleisli m) where
  arr f      = K (\b -> return (f b))
  K f >>> K g = K (\b -> f b >> g)
  
```

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Arrows and Monads (2)

But not every arrow is a monad. However, arrows that support an additional **apply** operation **are** effectively monads:

```
apply :: Arrow a => a (a b c, b) c
```

Exercise 6: Verify that

```
newtype M b = M (A () b)
```

is a monad if A is an arrow supporting **apply**; i.e., define **return** and **bind** in terms of the arrow operations (and verify that the monad laws hold).

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An application: FRP

Functional Reactive Programming (FRP):

- Paradigm for **reactive programming** in a functional setting:
 - Input arrives **incrementally** while system is running.
 - Output is generated in response to input in an interleaved and **timely** fashion.
- Originated from Functional Reactive Animation (Fran) (Elliott & Hudak).
- Has evolved in a number of directions and into different concrete implementations.

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Yampa

Yampa:

- The most recent Yale FRP implementation.
- Embedding** in Haskell (a Haskell library).
- Arrows** used as the basic structuring framework.
- Continuous time.**
- Discrete-time signals modelled by continuous-time signals and an option type.
- Advanced **switching constructs** allows for highly dynamic system structure.

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Related languages

FRP related to:

- Synchronous languages, like Esterel, Lucid Synchrone.
- Modeling languages, like Simulink.

Distinguishing features of FRP:

- First class reactive components.
- Allows highly dynamic system structure.
- Supports hybrid (mixed continuous and discrete) systems.

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FRP applications

Some domains where FRP has been used:

- Graphical Animation (Fran: Elliott, Hudak)
- Robotics (Frob: Peterson, Hager, Hudak, Elliott, Pembeci, Nilsson)
- Vision (FVision: Peterson, Hudak, Reid, Hager)
- GUIs (Fruit: Courtney)
- Hybrid modeling (Nilsson, Hudak, Peterson)

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Yampa?

Yampa is a river with long calmly flowing sections and abrupt whitewater transitions in between.

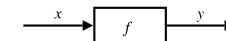


A good metaphor for hybrid systems!

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Signal functions

Key concept: **functions on signals.**



Intuition:

```

Signal α ≈ Time → α
x :: Signal T1
y :: Signal T2
SF α β ≈ Signal α → Signal β
f :: SF T1 T2
  
```

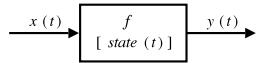
Additionally: **causality** requirement.

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Signal functions and state

Alternative view:

Signal functions can encapsulate **state**.



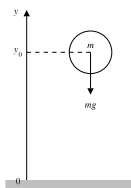
$state(t)$ summarizes input history $x(t')$, $t' \in [0, t]$.

Functions on signals are either:

- **Stateful:** $y(t)$ depends on $x(t)$ and $state(t)$
- **Stateless:** $y(t)$ depends only on $x(t)$

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Example: A bouncing ball



$$y = y_0 + \int v dt$$

$$v = v_0 + \int -9.81$$

On impact:

$$v = -v(t-)$$

(fully elastic collision)

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Example: Space Invaders



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Yampa and Arrows

SF is an arrow. Signal function instances of core combinators:

- `arr :: (a -> b) -> SF a b`
- `>>> :: SF a b -> SF b c -> SF a c`
- `first :: SF a b -> SF (a,c) (b,c)`
- `loop :: SF (a,c) (b,c) -> SF a b`

But `apply` has no useful meaning. Hence SF is **not a monad**.

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Part of a model of the bouncing ball

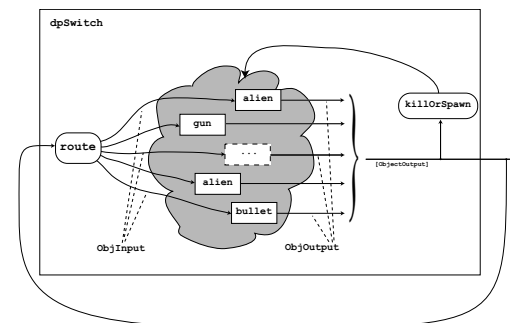
Free-falling ball:

```
type Pos = Double
type Vel = Double
```

```
fallingBall ::
  Pos -> Vel -> SF () (Pos, Vel)
fallingBall y0 v0 = proc () -> do
  v <- (v0 +) ^<< integral -< -9.81
  y <- (y0 +) ^<< integral -< v
  returnA -< (y, v)
```

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Overall game structure



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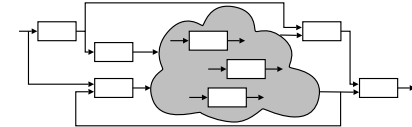
Some further basic signal functions

- `identity :: SF a a`
`identity = arr id`
- `constant :: b -> SF a b`
`constant b = arr (const b)`
- `integral :: VectorSpace a s=>SF a a`
- `time :: SF a Time`
`time = constant 1.0 >>> integral`
- `(^<<) :: (b->c) -> SF a b -> SF a c`
`f (^<<) sf = sf >>> arr f`

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Dynamic system structure

Switching allows the structure of the system to evolve over time:



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Reading

- John Hughes. Generalising monads to arrows. *Science of Computer Programming*, 37:67–111, May 2000
- John Hughes. Programming with arrows. In *Advanced Functional Programming*, 2004. To be published by Springer Verlag.
- Henrik Nilsson, Antony Courtney, and John Peterson. Functional reactive programming, continued. In *Proceedings of the 2002 Haskell Workshop*, pp. 51–64, October 2002.

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Reading (2)

- Paul Hudak, Antony Courtney, Henrik Nilsson, and John Peterson. Arrows, robots, and functional reactive programming. In *Advanced Functional Programming*, 2002. LNCS 2638, pp. 159–187.
- Antony Courtney, Henrik Nilsson, and John Peterson. The Yampa Arcade. In *Proceedings of the 2003 ACM SIGPLAN Haskell Workshop (Haskell'03)*, Uppsala, Sweden, 2003, pp 7–18.