All-Paths Algorithm

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Overview

- *Goal*: derive a single generic path-finding algorithm.
- Exploit algebraic properties common to a variety of path-finding problems.
- *Key idea*: property of being a Kleene algebra extends to graphs/matrices.
- Develop algorithm in two steps.
 - skeleton using operations on graphs,
 - detailed implementation using operations on edge labels.

Reachability Problem

Given is an $n \times n$ matrix G where g_{ij} is true if there is an edge from node numbered i to the node numbered j, and false otherwise. Determine, for each i and j, whether there is a path from i to j.

```
for k := 0 to n-1

do for i := 0 to n-1

do for j := 0 to n-1

do g_{ij} := g_{ij} \lor (g_{ik} \land g_{kj})

end_for

end_for

end_for
```

Least-Cost Paths

 g_{ij} represents the least *cost* of traversing an edge from node i to node j. Determine, for each i and j, the least cost of a path from i to j.

```
for k := 0 to n-1
do for i := 0 to n-1
do for j := 0 to n-1
do g_{ij} := g_{ij} \downarrow (g_{ik} + g_{kj})
end_for
end_for
```

Bottleneck Problem

 g_{ij} represents the height of the lowest underpass on the road connecting i and j. Determine, for each i and j, the height of the lowest underpass on the best route from from i to j.

```
for k := 0 to n-1

do for i := 0 to n-1

do for j := 0 to n-1

do g_{ij} := g_{ij} \uparrow (g_{ik} \downarrow g_{kj})

end_for

end_for
```

All Paths

Edge labels are letters of some alphabet and a path spells out a word. Determine, for each i and j, a regular expression representing all words spelt out by a path from i to j.

```
for k := 0 to n-1

do for i := 0 to n-1

do for j := 0 to n-1

do g_{ij} := g_{ij} + g_{ik}(g_{kk})^*g_{kj}

end_for

end_for
```

Selectors

N is the set of nodes of the graph.

- $\boldsymbol{i},\,\boldsymbol{j}$ and \boldsymbol{k} denote individual nodes of the graph.
- $L,\,M$ and P denote sets of nodes (i.e. subsets of N).

 $1 \times |N|$ and $|N| \times 1$ matrices are called *vectors*, 1×1 matrices will be called *scalars* and $|N| \times |N|$ matrices will be called *matrices*.

 $\langle \mathbf{k} |$ is the $1 \times |\mathbf{N}|$ vector that differs from 0 only in its kth component which is 1. Such a vector is called a *primitive selector vector*. The transpose of $\langle \mathbf{k} |$ (thus an $|\mathbf{N}| \times 1$ vector) is denoted by $|\mathbf{k} \rangle$.

We define the $|N| \times |N|$ primitive selector matrix <u>k</u> by the equation

$$\underline{\mathbf{k}} = |\mathbf{k}\rangle \cdot \langle \mathbf{k}| \quad . \tag{1}$$

Properties of Selectors

$$\underline{\mathbf{M}} = \langle \boldsymbol{\Sigma} \mathbf{k} : \mathbf{k} \in \mathbf{M} : \underline{\mathbf{k}} \rangle \tag{2}$$

$$\underline{\{k\}} = \underline{k} \tag{3}$$

$$X \cdot \underline{\phi} = \underline{\phi} \cdot X = \underline{\phi} \tag{4}$$

$$X \cdot \underline{\phi} = \underline{\phi} \cdot X = \underline{\phi} \tag{5}$$

$$\underline{\phi}^* = \mathbf{1} \tag{6}$$

$$\underline{\mathsf{L}} \cup \underline{\mathsf{M}} = \underline{\mathsf{L}} + \underline{\mathsf{M}} \tag{7}$$

$$\mathbf{X} \cdot \underline{\mathbf{N}} = \mathbf{X} = \underline{\mathbf{N}} \cdot \mathbf{X} \tag{8}$$

Identifying an Invariant

Assume $N = L \cup M$. Then,

$$\begin{split} G^* &= (\underline{N} \cdot G)^* = (\underline{L} \cup \underline{M} \cdot G)^* = (\underline{L} \cdot G + \underline{M} \cdot G)^* = (\underline{L} \cdot G)^* \cdot (\underline{M} \cdot G \cdot (\underline{L} \cdot G)^*)^* \ . \end{split}$$
 Thus,

$$\mathbf{G} \cdot \mathbf{G}^* = \mathbf{G} \cdot (\underline{\mathbf{L}} \cdot \mathbf{G})^* \cdot (\underline{\mathbf{M}} \cdot \mathbf{G} \cdot (\underline{\mathbf{L}} \cdot \mathbf{G})^*)^*$$
.

Define f(X, P) by

$$f(X, P) = X \cdot (\underline{P} \cdot X)^* \quad . \tag{9}$$

Then the above calculation establishes first that

$$\mathbf{G} \cdot \mathbf{G}^* = \mathbf{f}(\mathbf{G}, \mathbf{N}) \tag{10}$$

and

$$f(X, L \cup M) = f(X \cdot (\underline{L} \cdot X)^*, M) \quad . \tag{11}$$

Moreover, since $\underline{\phi} \cdot \mathbf{X} = \underline{\phi}$ and $\underline{\phi}^* = \mathbf{1}$,

 $f(X, \phi) = X \quad . \tag{12}$

Skeleton Algorithm (Continued)

Assume nodes are numbered from 0 through n-1. Thus, N = [0..n).

Reducing to Primitive Operations

 $X \cdot (\underline{k} \cdot X)^*$

 $= \{ \qquad \text{unfolding } (\underline{k} \cdot X)^* \}$

 $\mathbf{X} \cdot (\mathbf{1} + (\underline{\mathbf{k}} \cdot \mathbf{X})^* \cdot \underline{\mathbf{k}} \cdot \mathbf{X})$

 $= \{ distributivity, unit \}$

 $\mathbf{X} + \mathbf{X} \cdot (\underline{\mathbf{k}} \cdot \mathbf{X})^* \cdot \underline{\mathbf{k}} \cdot \mathbf{X}$

 $= \{ \underline{k} = |k\rangle \cdot \langle k| \}$

 $X + X \cdot (|k\rangle \cdot \langle k| \cdot X)^* \cdot |k\rangle \cdot \langle k| \cdot X$

 $= \{ \text{ mirror rule for } |k\rangle \}$ $X + X \cdot |k\rangle \cdot \langle k|X|k\rangle^* \cdot \langle k| \cdot X .$

Reducing to Primitive Operations

Reducing to Primitive Operations

 $X := X + X \cdot |k\rangle \cdot \langle k|X|k\rangle^* \cdot \langle k| \cdot X$

is directly implemented as the *simultaneous* assignment

 $\begin{array}{rcl} \mbox{simultaneously}\mbox{for} & (i := 0 \mbox{ to } n-1) \mbox{ and } (j := 0 \mbox{ to } n-1) \\ \mbox{ do } & \langle i|X|j\rangle \ := \ \langle i|X|j\rangle + \langle i|X|k\rangle \cdot \langle k|X|k\rangle^* \cdot \langle k|X|j\rangle \\ & \mbox{ end}\mbox{ for} \\ \mbox{Writing } & \langle i|X|j\rangle \mbox{ conventionally as } x_{ij} \\ & \mbox{ simultaneously}\mbox{ for } & (i := 0 \mbox{ to } n-1) \mbox{ and } (j := 0 \mbox{ to } n-1) \\ & \mbox{ do } x_{ij} \ := \ x_{ij} + x_{ik} \cdot (x_{kk})^* \cdot x_{kj} \\ & \mbox{ end}\mbox{ for } \end{array}$

Exploiting Idempotence

Mapping

 $X := X + X \cdot |k\rangle \cdot \langle k|X|k\rangle^* \cdot \langle k| \cdot X$

is a closure operator. Hence, it can be implemented using a destructive assignment:

X,k := G,0{ Invariant: $G^+ = X \cdot (\underline{P} \cdot X)^*$ where P = [k...n] } ; do $k \neq n \rightarrow$ for each pair (i,j), $0 \leq i,j < n$ do $x_{ij} := x_{ij} + x_{ik} \cdot (x_{kk})^* \cdot x_{kj}$ end_for ; k := k+1od $\{ G^+ = X \}$.