Dependent Type Theory of Stateful Higher-Order Functions

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- Type theory is a program logic:
 - types can express and enforce precise program properties
- Doubles up as a programming language.
- Prototypical higher-order language (e.g, polymorphism, inductive/recursive types, subset types, etc.)
- Problem: must be purely functional
 - recursion allowed, if you prove termination
 - effects like state, IO, etc., usually second class

- Logic for imperative programs.
- Specifies partial correctness via Hoare triple $\{P\} E \{Q\}$:
 - if P holds, then E diverges or terminates in a state Q
 - P: precondition
 - Q: postcondition
- Usually targets first-order languages
 - but recent advances in the higher-order case
- Reasoning about state and aliasing very streamlined
 - Separation Logic by O'Hearn, Pym, Reynolds, Yang...

Type theory for imperative programs

- Why not integrate Hoare Logic into a Type Theory?
- Benefits:
 - types can enforce correct use of effectful programs
 - add effects to type theory
 - preserves equational reasoning about pure programs
- Idea: follow specifications-as-types principle
 - Type of Hoare triples $\{P\}x:A\{Q\}$
 - precondition P, postcondition Q, return result of type A.
 - Dependencies allow P and Q to talk about program data.
- In this talk: Hoare Type Theory (HTT)
 - for reasoning about state and aliasing

Outline

- Introduction \checkmark
- Assertion logic
- Types and terms
- Typechecking
- Conclusions

- Partial functions, assigning to each natural number at most one value.
- Assertion seleq_{τ}(H, M, N):

- In the heap H, location M points to $N : \tau$.

- Function $upd_{\tau}(H, M, N)$:
 - Returns a new heap in which M points to $N : \tau$.
- τ is a monomorphic type.

• McCarthy's axioms for functional arrays.

(ax1) seleq_A(upd_A(H, M, N), M, N) (ax2) $M_1 \neq M_2 \land seleq_A(upd_B(H, M_1, N_1), M_2, N_2) \supset$ seleq_A(H, M₂, N₂)

• And:

(ax3) seleq_A(empty, M, N) $\supset \bot$ (ax4) seleq_A(H, M, N_1) \land seleq_A(H, M, N_2) $\supset N_1 = N_2$

- Classical multi-sorted first-order logic with equality
- Sorts: heaps and all types of HTT
- Plus: type polymorphism (predicative)
- Examples
 - heap equality can be defined:

 $H_1 = H_2 \equiv \forall l:$ nat. $\forall \alpha. \forall x: \alpha.$

 $\operatorname{seleq}_{\alpha}(H_1,l,x) \subset \supset \operatorname{seleq}_{\alpha}(H_2,l,x)$

- Also definable: disjoint union $H = H_1 \uplus H_2$

- We can define propositions from Separation Logic.
 - Variable mem denotes current heap.

 $\begin{array}{lll} \mathsf{emp} & \equiv & (\mathsf{mem} = \mathsf{empty}) \\ M \mapsto_{\tau} N & \equiv & (\mathsf{mem} = \mathsf{upd}_{\tau}(\mathsf{empty}, M, N)) \\ M \hookrightarrow_{\tau} N & \equiv & \mathsf{seleq}_{\tau}(\mathsf{mem}, M, N) \\ P \ast Q & \equiv & \exists h_1, h_2 : \mathsf{heap.}(\mathsf{mem} = h_1 \uplus h_2) \\ & & \land [h_1/\mathsf{mem}] P \land [h_2/\mathsf{mem}] Q \\ P \twoheadrightarrow Q & \equiv & \forall h_1, h_2 : \mathsf{heap.}(h_2 = h_1 \uplus \mathsf{mem}) \\ & & \supset [h_1/\mathsf{mem}] P \supset [h_2/\mathsf{mem}] Q \\ & \mathsf{this}(H) & \equiv & (\mathsf{mem} = H) \end{array}$

- Swap content of locations x and y (here natural numbers).
- Spec with no aliasing between x and y:
 - $-\alpha$, β : type variables

swap: $\forall \alpha. \forall \beta. \Pi x$:nat. Πy :nat.

$$\{ x \mapsto_{\alpha} m * y \mapsto_{\beta} n \} r : 1 \{ x \mapsto_{\beta} n * y \mapsto_{\alpha} m \}$$

• For a spec with aliasing, use \wedge instead of \ast

- Swap content of locations x and y (here natural numbers).
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swap: $\forall \alpha. \forall \beta. \Pi x:$ nat. $\Pi y:$ nat. $m: \alpha. n: \beta. \{x \mapsto_{\alpha} m * y \mapsto_{\beta} n\}r: 1$ $\{x \mapsto_{\beta} n * y \mapsto_{\alpha} m\}$

- For a spec with aliasing, use \land instead of *
- *m*, *n*: dummy variables

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- Primitive types: nat, bool, 1
- Dependent functions: $\Pi x:A$. B standard
- Polymorphic types: $\forall \alpha$. A standard
- Hoare types: $\{P\}x:A\{Q\}$
 - Hoare types are *monads*
 - encapsulate effectful computations
 - but also formalize reasoning by strongest postconditions

- Pure fragment: higher-order functions, polymorphism...
- Impure fragment first-order imperative language
 - sequence of commands, ending with a return value
 - primitives for allocation, strong update, lookup, deallocation, conditionals, recursion
 - recursive functions must be annotated with a type
- Monadic constructs:
 - dia E
 - $\cdot \,$ suspends the effectful computation E
 - suspension is pure, so it can appear in types
 - let dia x = M in E
 - $\cdot \;$ run M, then E

• Definition and typing of characteristic monadic terms:

unit :
$$A \to M(A) = \lambda x$$
. dia x

map :
$$(A \to B) \to M(A) \to M(B) =$$

 $\lambda f. \lambda x.$ dia (let dia $y = x$ in $f y$)
idemp : $M(M(A)) \to M(A) =$
 $\lambda x.$ dia (let dia $y = x$ in let dia $z = y$ in z)

• Definition and typing of characteristic monadic terms:

unit :
$$A \to M(A) = \lambda x$$
. dia x

$$\begin{array}{ll} \mathsf{map} & : & (A \to B) \to M(A) \to M(B) = \\ & \lambda f. \ \lambda x. \ \mathsf{dia} \ (\mathsf{let} \ \mathsf{dia} \ y = x \ \mathsf{in} \ f \ y) \\ \mathsf{idemp} & : & M(M(A)) \to M(A) = \\ & \lambda x. \ \mathsf{dia} \ (\mathsf{let} \ \mathsf{dia} \ y = x \ \mathsf{in} \ \mathsf{let} \ \mathsf{dia} \ z = y \ \mathsf{in} \ z) \end{array}$$

• Dependently typed unit:

unit' :
$$\Pi x:A$$
. $\{P\}y:A\{x = y \land P\} = \lambda x$. dia x

• Swap content of x and y

swap :
$$\forall \alpha. \forall \beta. \Pi x:$$
nat. $\Pi y:$ nat.
m: α . n: β . { $x \mapsto_{\alpha} m * y \mapsto_{\beta} n$ } r : unit
{ $x \mapsto_{\beta} n * y \mapsto_{\alpha} m$ } =
 $\Lambda \alpha. \Lambda \beta. \lambda x. \lambda y.$ dia (u = !x; v = !y;
y := u; x := v;
())

• Swapping twice in a row is identity.

 $\begin{array}{l} \text{identity} = \Lambda \alpha.\Lambda \beta.\lambda \textbf{x}.\lambda \textbf{y}. \ \text{dia}(\text{let dia}_{-} = \text{swap } \alpha \ \beta \ \textbf{x} \ \textbf{y} \\ & \text{dia}_{-} = \text{swap } \beta \ \alpha \ \textbf{x} \ \textbf{y} \\ & \text{in} \\ & () \\ & \text{end}) \end{array}$

— Heap invariance apparent from the type.

identity : $\forall \alpha. \forall \beta. \Pi x$:nat. Πy :nat. m: $\alpha,$ n: β ,h:heap. $\{(x \mapsto_{\alpha} m * y \mapsto_{\beta} n) \land \text{this}(h)\}$ r : 1 $\{\text{this}(h)\}$

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- Typechecking by computing strongest postconditions.
- Typechecking is completely syntax-directed.
 - effectful programs are (part of) the proofs of their specs
 - remaining part of the proof must discharge intermediate assertions
 - no whole-program reasoning
- Judgment: $\Delta; P \vdash E \Rightarrow x:A. Q$
 - $-\Delta$: variable context
 - *E*: computation
 - P: what holds before E runs (precondition)
 - A: return result
 - Q: how the heap is changed after E (strongest postcondition)
 - -Q is output

- deallocates memory at location M, and proceeds to run E

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• Typing rule:

$$\Delta \vdash M : \mathsf{nat}$$
$$\Delta \vdash P \supset (M \hookrightarrow -)$$

 $\Delta; P \vdash \mathsf{dealloc}(M); E \Rightarrow y : B. \ Q$

• proving $P \supset (M \hookrightarrow -)$ can be postponed

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• Typing rule:

$$\begin{array}{ll} \Delta \vdash M: \mathsf{nat} \\ \Delta \vdash P \supset (M \hookrightarrow -) \\ \vdots \\ E \Rightarrow y : B. \ Q \\ \hline \Delta; P \vdash \mathsf{dealloc}(M); E \Rightarrow y : B. \ Q \end{array}$$

• proving
$$P \supset (M \hookrightarrow -)$$
 can be postponed

- deallocates memory at location M, and proceeds to run E

• Typing rule:

$$\begin{array}{l} \Delta \vdash M : \mathsf{nat} \\ \Delta \vdash P \supset (M \hookrightarrow -) \\ \end{array}$$

$$\begin{array}{l} \Delta; P \circ ((M \mapsto -) \multimap \mathsf{emp}) \vdash E \Rightarrow y : B. \ Q \\ \end{array}$$

$$\begin{array}{l} \Delta; P \vdash \mathsf{dealloc}(M); E \Rightarrow y : B. \ Q \end{array}$$

- proving $P \supset (M \hookrightarrow -)$ can be postponed
- $P \circ (R_1 \multimap R_2)$ is a heap obtained by switching R_1 with R_2 in P
- connectives \circ and $-\circ$ definable in HTT, but independent of * and -*

- In addition to equational theory, we define call-by-value operational semantics
- Soundness must show that $P \vdash E \Rightarrow x:A$. Q indeed has the intuitive semantics
- Soundness requires Preservation and Progress (as usual in type systems) but here much stronger
- Preservation: evaluation preserves types and canonical forms.
- Progress: well-typed programs do not get stuck.
- Progress depends on the soundness of the assertion logic.
 - assertion logic soundness proved by simple denotational argument

- Extended static checking tools: ESC/Java, SPlint, Spec#, Cyclone...
 - Hoare-like annotations verified during type checking
 - but usually no semantic foundations
- Dependent types and effects ([Zhu, Xi'05], [Shao, Trifonov, Saha, Papaspyrou'05])
 - but types cannot depend on effectful programs
- Hoare Logic for higher-order functions ([Schröder,Mossakowski'02], [Honda, Berger, Yoshida'05])
 - simply typed underlying language (with effects)
 - Hoare triples *do not* integrate into a type system

- HTT is a type-theoretic version of Hoare Logic
 - dually: Hoare Logic for a dependently typed language
 - dually: Type Theory with monadic effects
- Specifications-as-types principle via monad $\{P\}x:A\{Q\}$
- Specifications like in Separation Logic.
- Definable connectives * and -* from Separation Logic (but new connectives o and --o also needed).
- Assertions checked by pushing strongest postconditions
- Proofs-as-programs principle (modulo proofs of assertion) guarantees no need for whole-program reasoning
- Paper available at: http://www.eecs.harvard.edu/~aleks

Future work

- Higher-order assertion logic
- Cook completeness
- Abstract types
- Local state
- Hoare logic for concurrency and runST

• Swapping twice in a row is identity.

```
      identity: \forall \alpha. \forall \beta. \Pi x: nat. \Pi y: nat. \\ m: \alpha, n: \beta, h: heap. \{ (x \mapsto_{\alpha} m * y \mapsto_{\beta} n) \land this(h) \} r: 1 \\ \{ this(h) \} = \\ \Lambda \alpha. \Lambda \beta. \lambda x. \lambda y. \ dia(let \ dia \ u = swap \ \alpha \ \beta x \ y \\ dia \ v = swap \ \beta \ \alpha x \ y \\ in \\ () \\ end)
```

- Equational theory [Pfenning, Davies'99]
- Implements monadic laws, but as β and η rules.

let dia $x = \text{dia } E \text{ in } F \implies_{\beta} \langle E/x \rangle F$ $M : \{P\}x:A\{Q\} \implies_{\eta} \text{ dia (let dia } x = M \text{ in } x)$

• Where $\langle E/x \rangle F$ is monadic linearization

 $\begin{array}{lll} \langle M/x\rangle F &=& [M/x]F\\ \langle {\rm command}; E''/x\rangle F &=& {\rm command}; \langle E''/x\rangle F\\ \langle {\rm let \ dia \ }y=E' \ {\rm in \ }E''/x\rangle F &=& {\rm let \ dia \ }y=E' \ {\rm in \ }\langle E''/x\rangle F \end{array}$

- Swap content of locations x and y (here natural numbers).
 - Spec with no aliasing between x and y:

swap: $\forall \alpha, \beta.\Pi x, y:$ nat. $m:\alpha.n:\beta.\{x \mapsto_{\alpha} m * y \mapsto_{\beta} n\}r: 1$ $\{x \mapsto_{\beta} n * y \mapsto_{\alpha} m\}$

- Spec with aliasing between x and y:

$$\begin{split} \mathsf{swap:} &\forall \alpha, \beta. \Pi x, y : \mathsf{nat.} \\ & m : \alpha. n : \beta. h : \mathsf{heap.} \{ x \hookrightarrow_{\alpha} m \land y \hookrightarrow_{\beta} n \land \mathsf{this}(h) \} r : \\ & \{ \mathsf{this}(\mathsf{upd}_{\beta}(\mathsf{upd}_{\alpha}(h, y, m), x, n)) \} \end{split}$$

• *m*, *n*, *h* – *dummy variables*

- $x = \operatorname{alloc}_{\tau}(M); E$
 - $-\,$ allocates memory and initializes with $M{:}\tau$
 - -x binds the address of allocated memory

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$$\Delta; P \vdash x = \operatorname{alloc}_{\tau}(M); E \Rightarrow y:B.$$

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 $\Delta \vdash \tau: \mathsf{type}$

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- -x binds the address of allocated memory
- Typing rule:

$$\begin{array}{c} \Delta \vdash \tau : \text{type} \\ \Delta \vdash M : \tau \end{array}$$

$$\Delta; P \vdash x = \operatorname{alloc}_{\tau}(M); E \Rightarrow y:B.$$

 $-\,$ allocates memory and initializes with $M{:}\tau$

- -x binds the address of allocated memory
- Typing rule:

$$\begin{array}{ll} \Delta \vdash \tau : \text{type} \\ \Delta \vdash M : \tau \\ \Delta, x: \text{nat}; & \vdash E \Rightarrow y: B. \ Q \\ \hline \Delta; P \vdash x = \text{alloc}_{\tau}(M); E \Rightarrow y: B. \end{array}$$

•
$$x = \operatorname{alloc}_{\tau}(M); E$$

- allocates memory and initializes with $M{:}\tau$

- -x binds the address of allocated memory
- Typing rule:

$$\Delta \vdash \tau : \mathsf{type}$$
$$\Delta \vdash M : \tau$$
$$\Delta, x:\mathsf{nat}; P * (x \mapsto_{\tau} M) \vdash E \Rightarrow y:B. \ Q$$
$$\overline{\Delta}; P \vdash x = \mathsf{alloc}_{\tau}(M); E \Rightarrow y:B. \ (\exists x:\mathsf{nat}.Q)$$

• $P * (x \mapsto_{\tau} M)$ means x disjoint from P, and hence *fresh*.

Typechecking letdia

• Typing rule:

$\Delta; P \vdash \text{let dia } x = K \text{ in } E \Rightarrow y:B. (\exists x:A. Q)$

Typechecking letdia

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$$\Delta \vdash K : \{R_1\} x : A\{R_2\}$$

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Typechecking letdia

• Typing rule:

$$\Delta \vdash K : \{R_1\} x : A\{R_2\}$$
$$\Delta \vdash P \supset R_1 * \top$$

$$\Delta; P \vdash$$
 let dia $x = K$ in $E \Rightarrow y:B. (\exists x:A. Q)$

• $P \supset R_1 * \top$ implements "small footprints"

• Typing rule:

$$\begin{array}{l} \Delta \vdash K : \{R_1\}x : A\{R_2\} \\ \Delta \vdash P \supset R_1 * \top \\ \Delta, x : A; P \circ (R_1 \multimap R_2) \vdash E \Rightarrow y : B. \ Q \\ \hline \Delta; P \vdash \text{ let dia } x = K \text{ in } E \Rightarrow y : B. \ (\exists x : A. \ Q) \end{array}$$

• $P \supset R_1 * \top$ implements "small footprints"

• Typing rule:

$$\frac{\Delta; R_1 * \top \vdash E \Rightarrow x : A. P \quad \Delta \vdash P \supset R_1 \multimap R_2}{\Delta \vdash \operatorname{dia} E : \{R_1\} x : A\{R_2\}}$$

- Precondition $R_1 * \top$:
 - E can run in any heap with a fragment R_1
- Strongest postcondition P must imply $R_1 \multimap R_2$
 - the ending heap obtained from initial by swapping R_1 with R_2